



NEXCOM International Co., Ltd.

Industrial Computing Solutions

Video Intelligent Surveillance

NViS 2140H

User Manual

NEXCOM International Co., Ltd.

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PREFACE

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Acknowledgements

NViS 2140H is a trademark of NEXCOM International Co., Ltd. All other product names mentioned herein are registered trademarks of their respective owners.

Regulatory Compliance Statements

This section provides the FCC compliance statement for Class A devices and describes how to keep the system CE compliant.

Declaration of Conformity

FCC

This equipment has been tested and verified to comply with the limits for a Class A digital device, pursuant to Part 15 of FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. Operation of this equipment in a residential area (domestic environment) is likely to cause harmful interference, in which case the user will be required to correct the interference (take adequate measures) at their own expense.

CE

The product(s) described in this manual complies with all applicable European Union (CE) directives if it has a CE marking. For computer systems to remain CE compliant, only CE-compliant parts may be used. Maintaining CE compliance also requires proper cable and cabling techniques.

RoHS Compliance



NEXCOM RoHS Environmental Policy and Status Update

NEXCOM is a global citizen for building the digital infrastructure. We are committed to providing green products and services, which are compliant with European Union

RoHS (Restriction on Use of Hazardous Substance in Electronic Equipment) directive 2002/95/EU, to be your trusted green partner and to protect our environment.

RoHS restricts the use of Lead (Pb) < 0.1% or 1,000ppm, Mercury (Hg) < 0.1% or 1,000ppm, Cadmium (Cd) < 0.01% or 100ppm, Hexavalent Chromium (Cr6+) < 0.1% or 1,000ppm, Polybrominated biphenyls (PBB) < 0.1% or 1,000ppm, and Polybrominated diphenyl Ethers (PBDE) < 0.1% or 1,000ppm.

In order to meet the RoHS compliant directives, NEXCOM has established an engineering and manufacturing task force in to implement the introduction of green products. The task force will ensure that we follow the standard NEXCOM development procedure and that all the new RoHS components and new manufacturing processes maintain the highest industry quality levels for which NEXCOM are renowned.

The model selection criteria will be based on market demand. Vendors and suppliers will ensure that all designed components will be RoHS compliant.

How to recognize NEXCOM RoHS Products?

For existing products where there are non-RoHS and RoHS versions, the suffix "(LF)" will be added to the compliant product name.

All new product models launched after January 2006 will be RoHS compliant. They will use the usual NEXCOM naming convention.

Warranty and RMA

NEXCOM Warranty Period

NEXCOM manufactures products that are new or equivalent to new in accordance with industry standard. NEXCOM warrants that products will be free from defect in material and workmanship for 2 years, beginning on the date of invoice by NEXCOM. HCP series products (Blade Server) which are manufactured by NEXCOM are covered by a three year warranty period.

NEXCOM Return Merchandise Authorization (RMA)

- ✘ Customers shall enclose the “NEXCOM RMA Service Form” with the returned packages.
- ✘ Customers must collect all the information about the problems encountered and note anything abnormal or, print out any on-screen messages, and describe the problems on the “NEXCOM RMA Service Form” for the RMA number apply process.
- ✘ Customers can send back the faulty products with or without accessories (manuals, cable, etc.) and any components from the card, such as CPU and RAM. If the components were suspected as part of the problems, please note clearly which components are included. Otherwise, NEXCOM is not responsible for the devices/parts.
- ✘ Customers are responsible for the safe packaging of defective products, making sure it is durable enough to be resistant against further damage and deterioration during transportation. In case of damages occurred during transportation, the repair is treated as “Out of Warranty.”

- ✘ Any products returned by NEXCOM to other locations besides the customers’ site will bear an extra charge and will be billed to the customer.

Repair Service Charges for Out-of-Warranty Products

NEXCOM will charge for out-of-warranty products in two categories, one is basic diagnostic fee and another is component (product) fee.

System Level

- ✘ Component fee: NEXCOM will only charge for main components such as SMD chip, BGA chip, etc. Passive components will be repaired for free, ex: resistor, capacitor.
- ✘ Items will be replaced with NEXCOM products if the original one cannot be repaired. Ex: motherboard, power supply, etc.
- ✘ Replace with 3rd party products if needed.
- ✘ If RMA goods can not be repaired, NEXCOM will return it to the customer without any charge.

Board Level

- ✘ Component fee: NEXCOM will only charge for main components, such as SMD chip, BGA chip, etc. Passive components will be repaired for free, ex: resistors, capacitors.
- ✘ If RMA goods can not be repaired, NEXCOM will return it to the customer without any charge.

Warnings

Read and adhere to all warnings, cautions, and notices in this guide and the documentation supplied with the chassis, power supply, and accessory modules. If the instructions for the chassis and power supply are inconsistent with these instructions or the instructions for accessory modules, contact the supplier to find out how you can ensure that your computer meets safety and regulatory requirements.

Cautions

Electrostatic discharge (ESD) can damage system components. Do the described procedures only at an ESD workstation. If no such station is available, you can provide some ESD protection by wearing an antistatic wrist strap and attaching it to a metal part of the computer chassis.

Safety Information

Before installing and using the device, note the following precautions:

- Read all instructions carefully.
- Do not place the unit on an unstable surface, cart, or stand.
- Follow all warnings and cautions in this manual.
- When replacing parts, ensure that your service technician uses parts specified by the manufacturer.
- Avoid using the system near water, in direct sunlight, or near a heating device.
- The load of the system unit does not solely rely for support from the rackmounts located on the sides. Firm support from the bottom is highly necessary in order to provide balance stability.
- The computer is provided with a battery-powered real-time clock circuit. There is a danger of explosion if battery is incorrectly replaced. Replace only with the same or equivalent type recommended by the manufacturer. Discard used batteries according to the manufacturer's instructions.

Installation Recommendations

Ensure you have a stable, clean working environment. Dust and dirt can get into components and cause a malfunction. Use containers to keep small components separated.

Adequate lighting and proper tools can prevent you from accidentally damaging the internal components. Most of the procedures that follow require only a few simple tools, including the following:

- A Philips screwdriver
- A flat-tipped screwdriver
- A grounding strap
- An anti-static pad

Using your fingers can disconnect most of the connections. It is recommended that you do not use needlenose pliers to disconnect connections as these can damage the soft metal or plastic parts of the connectors.

Safety Precautions

1. Read these safety instructions carefully.
2. Keep this User Manual for later reference.
3. Disconnect this equipment from any AC outlet before cleaning. Use a damp cloth. Do not use liquid or spray detergents for cleaning.
4. For plug-in equipment, the power outlet socket must be located near the equipment and must be easily accessible.
5. Keep this equipment away from humidity.
6. Put this equipment on a stable surface during installation. Dropping it or letting it fall may cause damage.
7. Do not leave this equipment in either an unconditioned environment or in a above 40°C storage temperature as this may damage the equipment.
8. The openings on the enclosure are for air convection to protect the equipment from overheating. DO NOT COVER THE OPENINGS.
9. Make sure the voltage of the power source is correct before connecting the equipment to the power outlet.
10. Place the power cord in a way so that people will not step on it. Do not place anything on top of the power cord. Use a power cord that has been approved for use with the product and that it matches the voltage and current marked on the product's electrical range label. The voltage and current rating of the cord must be greater than the voltage and current rating marked on the product.
11. All cautions and warnings on the equipment should be noted.
12. If the equipment is not used for a long time, disconnect it from the power source to avoid damage by transient overvoltage.
13. Never pour any liquid into an opening. This may cause fire or electrical shock.
14. Never open the equipment. For safety reasons, the equipment should be opened only by qualified service personnel.
15. If one of the following situations arises, get the equipment checked by service personnel:
 - a. The power cord or plug is damaged.
 - b. Liquid has penetrated into the equipment.
 - c. The equipment has been exposed to moisture.
 - d. The equipment does not work well, or you cannot get it to work according to the user's manual.
 - e. The equipment has been dropped and damaged.
 - f. The equipment has obvious signs of breakage.
16. Do not place heavy objects on the equipment.
17. The unit uses a three-wire ground cable which is equipped with a third pin to ground the unit and prevent electric shock. Do not defeat the purpose of this pin. If your outlet does not support this kind of plug, contact your electrician to replace your obsolete outlet.
18. CAUTION: DANGER OF EXPLOSION IF BATTERY IS INCORRECTLY REPLACED. REPLACE ONLY WITH THE SAME OR EQUIVALENT TYPE RECOMMENDED BY THE MANUFACTURER. DISCARD USED BATTERIES ACCORDING TO THE MANUFACTURER'S INSTRUCTIONS.
19. The computer is provided with CD drives that comply with the appropriate safety standards including IEC 60825.

Technical Support and Assistance

1. For the most updated information of NEXCOM products, visit NEXCOM's website at www.nexcom.com.
2. For technical issues that require contacting our technical support team or sales representative, please have the following information ready before calling:
 - Product name and serial number
 - Detailed information of the peripheral devices
 - Detailed information of the installed software (operating system, version, application software, etc.)
 - A complete description of the problem
 - The exact wordings of the error messages

Warning!

1. Handling the unit: carry the unit with both hands and handle it with care.
2. Maintenance: to keep the unit clean, use only approved cleaning products or clean with a dry cloth.
3. CompactFlash: Turn off the unit's power before inserting or removing a CompactFlash storage card.

Conventions Used in this Manual



Warning: Information about certain situations, which if not observed, can cause personal injury. This will prevent injury to yourself when performing a task.



Caution: Information to avoid damaging components or losing data.



Note: Provides additional information to complete a task easily.

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<http://www.nexcom-jp.com>

PACKAGE CONTENTS

Before continuing, verify that the NViS 2140H package that you received is complete. Your package should have all the items listed in the following table.

Item	Part Number	Description		Qty
1	50311F0110X00	(H)FLAT HEAD SCREW LONG FEI:F3x5ISO+NYLOK NIGP		4
2	602DCD0337X00	(N)NISE2100 CD DRIVER VER:2.0		1
3	60177A0223X00	(N)NISE2100 QUICK REFERENCE GUIDE VER:A		1
4	4NCPF00310X00	(N)TERMINAL BLOCKS 3P PHOENIX CONTACT:1803581		1
5	4NCPF00204X00	TERMINAL BLOCKS 2P PHOENIX CONTACT:1777989		1
6		1. D-Type integrated cable Video & Audio input x4 TV-out x2 2. Surveillance system user manual 3. Surveillance CD/driver		1

ORDERING INFORMATION

The following provides ordering information for NViS 2140H.

- **NViS 2140 (P/N: TBD) RoHS Compliant**
 - Intel® Atom™ Dual Core D525 fanless system
- **19V, 120W AC/DC power adapter w/o power core (P/N: 7410120002X00)**

CHAPTER 1: PRODUCT INTRODUCTION

Overview



Front



Rear

Key Features

- Onboard Intel® Atom™ Dual Core D525 (1.8GHz, 1M cache) processor
- One DDR3 SODIMM socket, DDR3 800, maximum of 2GB memory module
- 2 x Intel® 1000/100/10 Mbps LAN ports
- 4 x USB 2.0
- 1 x VGA
- 1 x DB15 GPIO connector
- 4 x RS232 and 2 x RS232/422/485 with auto flow control
- One external CF socket
- One external SIM card holder
- 9 ~ 36V DC input
- ATX power mode
- 1 4-channel full-D1 SD capture card supports 4-channel hybrid mobile DVR

Hardware Specifications

Main Board

- NISB 2100A
- Onboard Intel® Atom™ D525 dual core processor, 1.8GHz, 1M cache
- Intel® ICH8M PCH

Main Memory

- One 204-pin DDR3 SODIMM socket
- Supports up to 2GB DDR3 800MHz SDRAM memory module, unbuffered, non-ECC

Expansion

- One mini-PCIe socket (for optional WiFi or mobile wireless module)
- Two antenna holes
- One external accessible SIM card holder

Ethernet

- 2 x Intel 82574L Gigabit LAN controllers

Storage

- 1 x 2.5" SATA HDD drive bay
- 1 x external CF socket

I/O Interface - Front

- ATX Power on/off switch
- HDD access / Power status LEDs
- 1 x DB15 GPIO connector (4-in/4-out)
- 2 x Serial ports (RS232)
- 2 x USB 2.0 ports
- 1 x CompactFlash socket
- 1 x external SIM card holder
- 2 x antenna holes (for optional WiFi or mobile wireless module)

I/O Interface - Rear

- 9~36V DC input
- 1 x 3-pin connector for remote power on/off switch
- 1 x DB15 VGA port
- 1 x speaker-out jack
- 2 x Intel® GbE LAN ports
- 2 x USB 2.0 ports
- 4 x Serial ports (2x RS232 and 2x RS232/422/485 with auto-flow control: isolation protection on COM1 and COM2)
- 4-channel full-D1 SD capture card supports 4-channel hybrid mobile DVR

DVR Features

- Video input
 - Default 4 channels (mixed IP and/or CCTV camera)
- Audio input
 - Default 4 channels
- Display rate
 - Total 120 FPS (NTSC), 100 FPS (PAL) @ D1
- Recording rate
 - Total 120 FPS (NTSC) / 100FPS (PAL) @ D1 (720x480) Real-time
- Resolution Format
 - 720x480, 720x576, 720x240, 720x288, 320x240
- TV-out support
 - 2 x BNC connectors
- Codec
 - H.264/Mpge4/Mjpeg
- Surveillance Software
 - NViS v1.53 Intelligent Surveillance Software Suite (Motion detection / Sensor detection / Scene change detection / Manual trigger detection)

Power Requirements

- ATX Power mode
- DC to DC power design onboard, supports 9~36V DC
- Optional 19V, 65W power adapter

Dimensions

- 195mm (W) x 200mm (D) x 90mm (H) (7.7" x 7.9" x 3.5")

Construction

- Aluminum chassis with fanless design

Environment

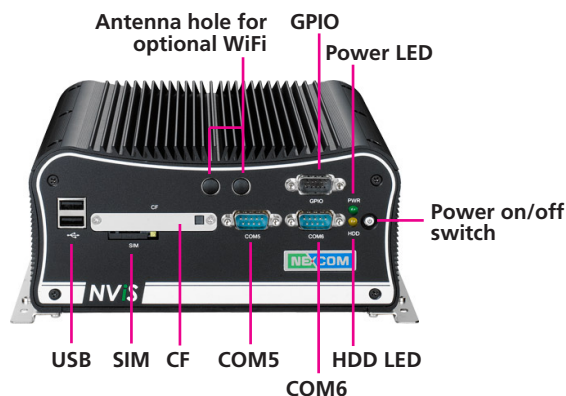
- Operating temperature
 - Ambient with airflow: -20°C to 70°C (with industrial CF and SSD condition)
 - According to IEC60068-2-1, IEC60068-2-2, IEC60068-2-14
- Storage temperature: -20°C to 80°C
- Relative humidity: 10% to 93% (Non-Condensing)

Certifications

- CE approval
- FCC Class A
- e13 Mark

Getting to Know NViS 2140H

Front Panel



USB

Used to connect USB 2.0/1.1 devices.

CF

Used to insert a CompactFlash card.

SIM

Used to insert a SIM card.

Antenna Hole for Optional WiFi

Used to connect an optional Mini-PCIe WiFi module.

COM5 and COM6

Used to connect RS232 compatible serial devices.

GPIO

The GPIO connector supports 4 digital input and 4 digital output.

Power LED

Indicates the power status of the system.

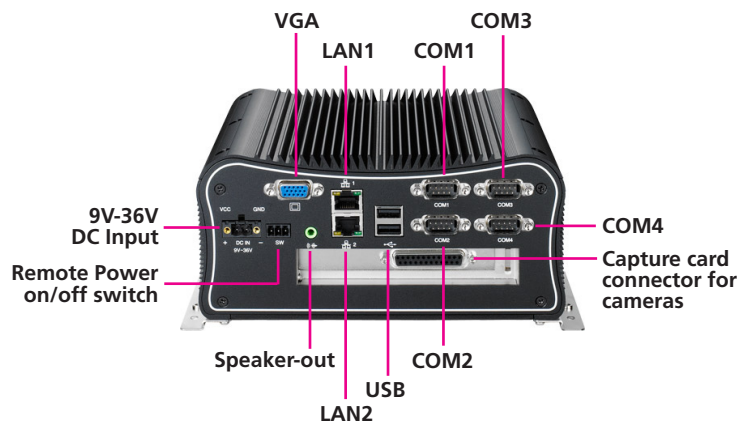
HDD LED

Indicates the status of the hard drive.

Power On/Off Switch

Press to power-on or power-off the system.

Rear Panel



9V-36V DC Input

Used to plug a DC power cord.

Output for Remote Power On/Off Switch

Used to connect a remote to power on/off the system.

VGA

Used to connect an analog VGA monitor.

Speaker-out

Used to connect a headphone or a speaker.

USB

Used to connect USB 2.0/1.1 devices.

LAN

Used to connect the system to a local area network.

COM1 and COM2

Used to connect RS232/422/485 compatible serial devices.

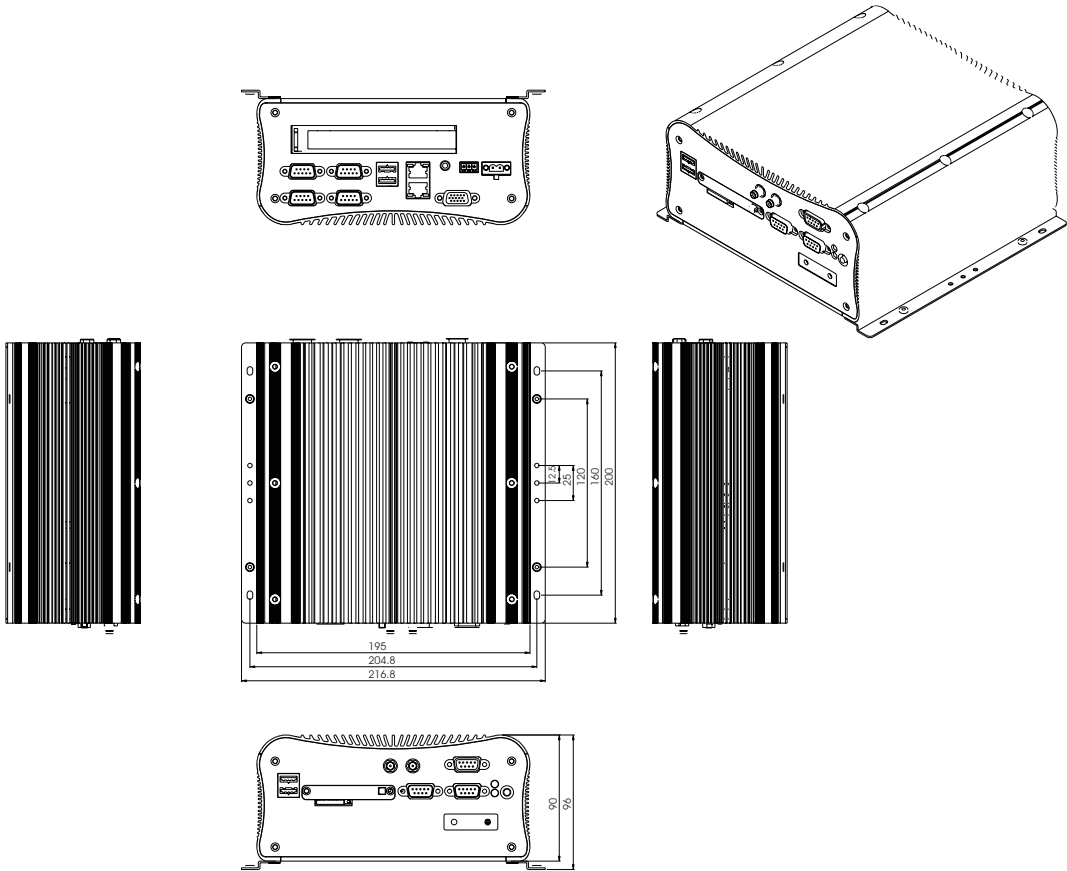
COM3 and COM4

Used to connect RS232 compatible serial devices.

Capture Card

Supports 4-channel full-D1 SD feature.

Mechanical Dimensions



CHAPTER 2: JUMPERS AND CONNECTORS

This chapter describes the jumpers and connectors on the motherboard. Note that the following procedures are generic for all NViS 2140H.

Before You Begin

- Ensure you have a stable, clean working environment. Dust and dirt can get into components and cause a malfunction. Use containers to keep small components separated.
- Adequate lighting and proper tools can prevent you from accidentally damaging the internal components. Most of the procedures that follow require only a few simple tools, including the following:
 - A Philips screwdriver
 - A flat-tipped screwdriver
 - A set of jewelers Screwdrivers
 - A grounding strap
 - An anti-static pad
- Using your fingers can disconnect most of the connections. It is recommended that you do not use needle-nosed pliers to disconnect connections as these can damage the soft metal or plastic parts of the connectors.
- Before working on internal components, make sure that the power is off. Ground yourself before touching any internal components, by touching a metal object. Static electricity can damage many of the electronic components. Humid environment tend to have less static electric-

ity than dry environments. A grounding strap is warranted whenever danger of static electricity exists.

Precautions

Computer components and electronic circuit boards can be damaged by discharges of static electricity. Working on the computers that are still connected to a power supply can be extremely dangerous.

Follow the guidelines below to avoid damage to your computer or yourself:

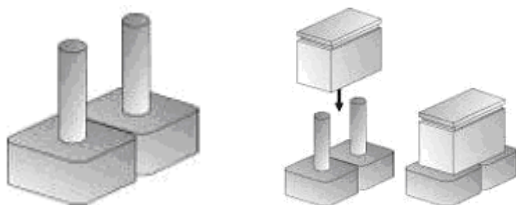
- Always disconnect the unit from the power outlet whenever you are working inside the case.
- If possible, wear a grounded wrist strap when you are working inside the computer case. Alternatively, discharge any static electricity by touching the bare metal chassis of the unit case, or the bare metal body of any other grounded appliance.
- Hold electronic circuit boards by the edges only. Do not touch the components on the board unless it is necessary to do so. Don't flex or stress the circuit board.
- Leave all components inside the static-proof packaging that they shipped with until they are ready for installation.
- Use correct screws and do not over tighten screws.

Jumper Settings

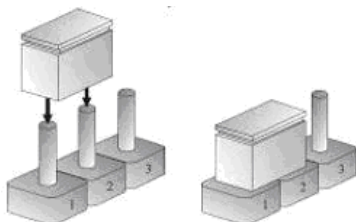
A jumper is the simplest kind of electric switch. It consists of two metal pins and a cap. When setting the jumpers, ensure that the jumper caps are placed on the correct pins. When the jumper cap is placed on both pins, the jumper is **short**. If you remove the jumper cap, or place the jumper cap on just one pin, the jumper is **open**.

Refer to the illustrations below for examples of what the 2-pin and 3-pin jumpers look like when they are short (on) and open (off).

Two-Pin Jumpers: Open (Left) and Short (Right)



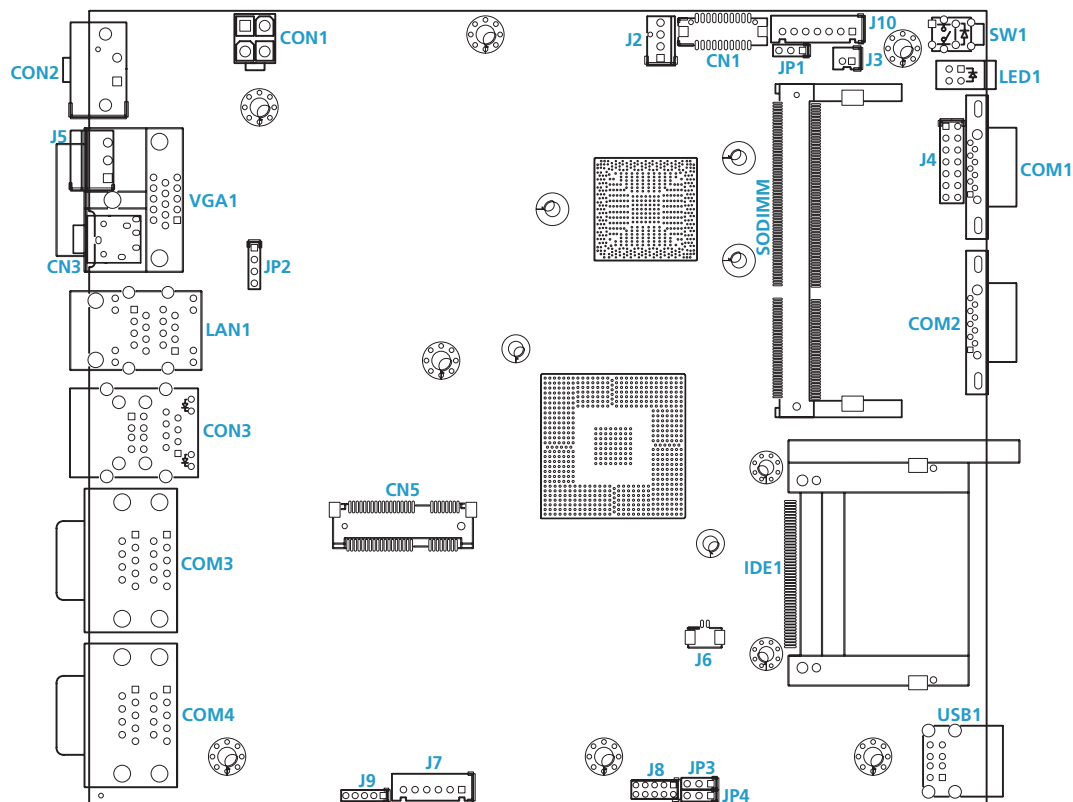
Three-Pin Jumpers: Pins 1 and 2 Are Short



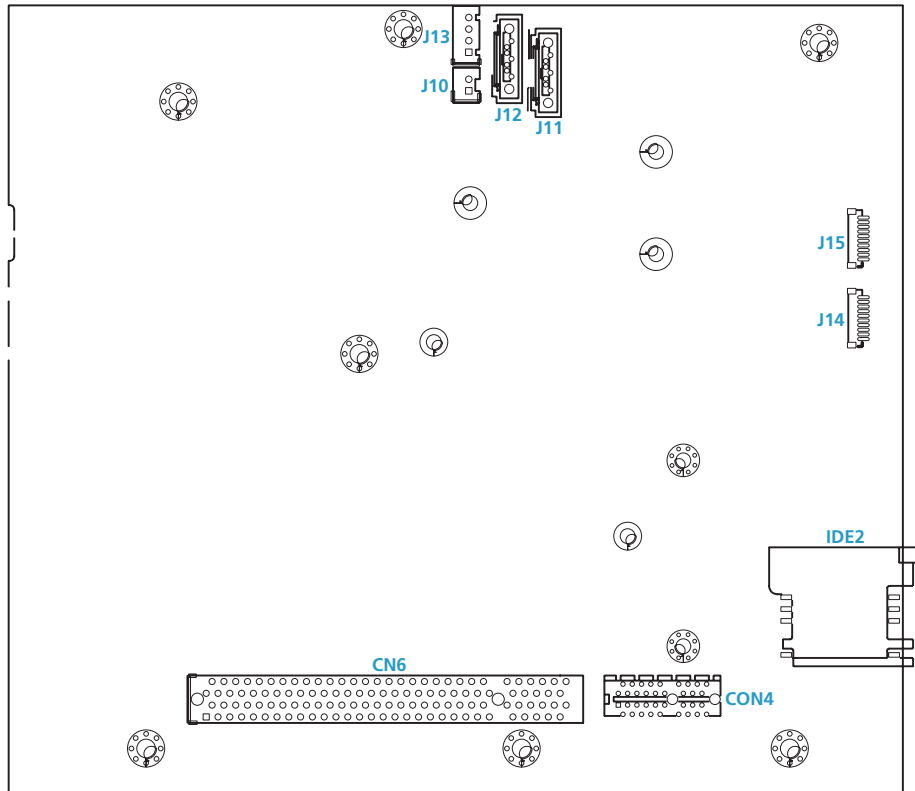
Locations of the Jumpers and Connectors

NISB 2100

The figure below is the top view of the NISB 2100 main board which is the main board used in the NViS 2140H system. It shows the locations of the jumpers and connectors.



The figure below is the bottom view of the NISB 2100 main board.



Jumpers

Clear CMOS

Connector type: 1x3 3-pin header, 2.54 mm pitch
Connector location: JP3



Pin	Settings
1-2 On	Normal
2-3 On	CMOS Clear

1-2 On: default

Pin	Definition
1	NC
2	IRTCRST#
3	GND

COM3 RS232 RI Pin Power Select

Connector type: 1x5 5-pin header 2.54mm -M-180
Connector location: J9



Pin	Settings
1-2	+5V
2-3	+12V
4-5	RING

4-5 On: default

Pin	Definition
1	VCC5
2	RING_T
3	+12V
4	RING_T
5	RING



Panel CCFL LVDS Backlight Power Select

Connector type: 1x3 3-pin header, 2.54 mm pitch
Connector location: JP1



Pin	Settings
1	VCC3 (3.3V)
2	VCC_LCD
3	VCC5(+5V)

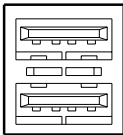
1-2 On: default

Connector Pin Definitions

External I/O Interface - Front Panel

USB Ports

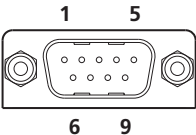
Connector type: Dual USB port
Connector location: USB1



Pin	Definition	Pin	Definition
1	USB_VCC(5V)	5	USB_VCC(5V)
2	DATA_N	6	DATA_N
3	DATA_P	7	DATA_P
4	GND	8	GND

COM5 Serial Port

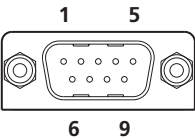
Connector type: DB-9 port
Connector location: COM2



Pin	Definition	Pin	Definition
1	COM5_DCD	6	COM5_DSR
2	COM5_RXD	7	COM5_RTS
3	COM5_TXD	8	COM5_CTS
4	COM5_DTR	9	COM5_RI
5	GND		

COM6 Serial Port

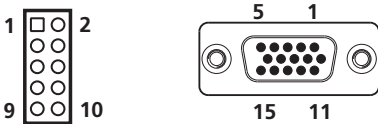
Connector type: DB-9 port
Connector location: COM1



Pin	Definition	Pin	Definition
1	COM6_DCD	6	COM6_DSR
2	COM6_RXD	7	COM6_RTS
3	COM6_TXD	8	COM6_CTS
4	COM6_DTR	9	COM6_RI
5	GND		

GPIO Connector

(4 digital input and 4 digital output)
Connector type: DB-15 port, 2x5 10-pin header, 2.0 mm-M-180
Connector location: J8



Pin	Definition	Pin	Definition
1	+5V	2	GND
3	GPO	4	GPI
5	GPO	6	GPI
7	GPO	8	GPI
9	GPO	10	GPI

Status Indicators

PWR



HDD

Status	LED Color
PWR	Green
HDD	Yellow

ATX Power On/Off Switch

Connector location: SW1



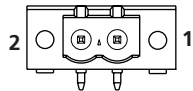
Pin	Definition
On	Blue light
Off	Red light

Pin	Definition	Pin	Definition
1	GND	2	PBT_PU
3	PBT_PU	4	GND
A1	PWRLED_N	C1	PWRLED_P

External I/O Interface - Rear Panel

9-36V DC Input

Connector type: 2P Phoenix Contact 5.08mm Power Connector
Connector location: CON2



Pin	Definition
1	GND
2	VIN(9~36V)

Remote Power On/Off Switch

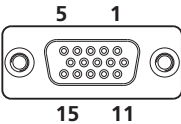
Connector type: 3-pin switch
Connector location: J5



Pin	Definition
1	GND
2	PWR_ON
3	PS_ON

VGA Port

Connector type: DB-15 port, 15-pin D-Sub
Connector location: VGA1



Pin	Definition	Pin	Definition
1	RED_VGA	9	VGA_VCC(5V)
2	GREEN_VGA	10	GND
3	BLUE_VGA	11	NC
4	NC	12	DDCDATA_VGA
5	GND	13	HSYNC_VGA
6	VGADET	14	VSYNC_VGA
7	GND	15	DDCCLK_VGA
8	GND		

Speaker-out Jack

Connector type: 6-pin jack
Connector location: CN3

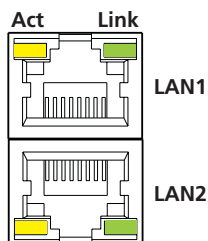


Pin	Definition
1	Speak Out - R
2	Speak Out - JD
3	NC
4	Speak Out - L
5	GND
6	GND

LAN Ports

Connector type: RJ45 port with LEDs

Connector location: LAN1



Act	Status
Yellow Blinking	Data Activity
Off	No Activity

Link	Status
Green Always Lighted	Linked
Off	No Link

LAN1

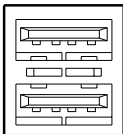
Pin	Definition	Pin	Definition
B1	LAN1M0P	B7	LAN1M3P
B2	LAN1M0N	B8	LAN1M3N
B3	LAN1M1P	B9	LAN1LINK
B4	LAN1M2P	B10	LAN1ACTP
B5	LAN1M2N	B11	LAN1ACT#
B6	LAN1M1N	B12	LAN1LINKP

LAN2

Pin	Definition	Pin	Definition
A1	LAN2M0P	A7	LAN2M3P
A2	LAN2M0N	A8	LAN2M3N
A3	LAN2M1P	A9	LAN2LINK
A4	LAN2M2P	A10	LAN2ACTP
A5	LAN2M2N	A11	LAN2ACT#
A6	LAN2M1N	A12	LAN2LINKP

USB Ports

Connector type: Dual USB port
Connector location: CON3

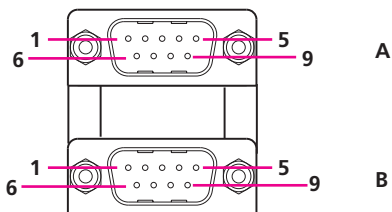


Pin	Definition	Pin	Definition
1	+5V	7	USB1+
2	USB0-	8	GND
3	USB0+	22	GND
4	GND	23	GND
5	+5V	26	GND
6	USB1-	27	GND

COM1 and COM2 Ports

Connector type: DB-9 port

Connector location: COM3



COM1A

Pin	Definition	Pin	Definition
1	COM1_DCD	6	COM1_DSR
2	COM1_RXD	7	COM1_RTS
3	COM1_TXD	8	COM1_CTS
4	COM1_DTR	9	COM1_RI
5	GND		

COM2B

Pin	Definition	Pin	Definition
1	COM2_DCD	6	COM2_DSR
2	COM2_RXD	7	COM2_RTS
3	COM2_TXD	8	COM2_CTS
4	COM2_DTR	9	COM2_RI
5	GND		

RS485

Pin	Definition	Pin	Definition
1	TXD-	6	Reserved
2	TXD+	7	Reserved
3	Reserved	8	Reserved
4	Reserved	9	Reserved
5	Reserved		

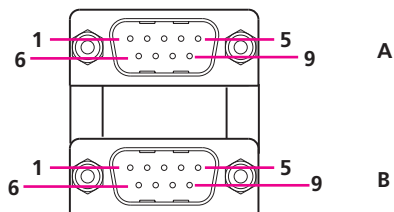
RS422

Pin	Definition	Pin	Definition
1	TXD-	6	RTS-
2	TXD+	7	RTS+
3	RXD+	8	CTS+
4	RXD-	9	CTS-
5	GND		

COM3 and COM4 Ports

Connector type: DB-9 port

Connector location: COM4



COM3A

Pin	Definition	Pin	Definition
1	COM3_DCD	6	COM3_DSR
2	COM3_RXD	7	COM3_RTS
3	COM3_TXD	8	COM3_CTS
4	COM3_DTR	9	COM3_RI
5	GND		

COM4B

Pin	Definition	Pin	Definition
1	COM4_DCD	6	COM4_DSR
2	COM4_RXD	7	COM4_RTS
3	COM4_TXD	8	COM4_CTS
4	COM4_DTR	9	COM4_RI
5	GND		

Internal Connectors

COM5 Connector

Connector type: 2x5 10-pin boxed header, 1.0mm
Connector location: J14



Pin	Definition	Pin	Definition
1	SIO_DCD#5	2	SIO_RXD5
3	SIO_TXD5	4	SIO_DTR#5
5	IO_GND	6	SIO_DSR#5
7	SIO_RTS#5	8	SIO_CTS#5
9	SIO_RI#5	10	IO_GND

COM6 Connector

Connector type: 2x5 10-pin boxed header, 1.0mm
Connector location: J15



Pin	Definition	Pin	Definition
1	SIO_DCD#6	2	SIO_RXD6
3	SIO_TXD6	4	SIO_DTR#6
5	IO_GND	6	SIO_DSR#6
7	SIO_RTS#6	8	SIO_CTS#6
9	SIO_RI#6	10	IO_GND

Remote Power On/Off Switch

Connector type: 1x2 2-pin header, JST 2.0mm
Connector location: J3



Pin	Definition
1	PSON#
2	GND

CPU Fan Connector

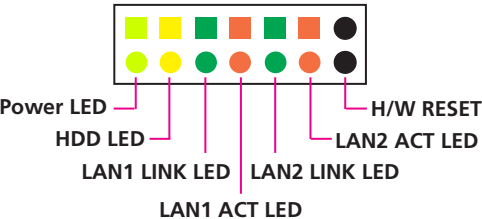
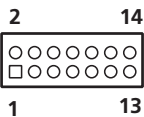
Connector type: 1x4, 4-pin Wafer, 2.54mm-M-180
Connector location: J2



Pin	Definition
1	GND
2	VCC_12
3	CPU1_FAN_SPEED
4	CPU1_FANPWM

Internal Power/HDD/LAN Power/LAN Active LED (RTC Connector)

Connector type: 2x7 14-pin header 2.54mm-M-180
Connector location: J4



Pin	Description	Pin	Description
1	POWER_OK	2	VCC_LEDPOWER
3	HDD_LED#	4	HDD_LEDPOWER
5	LAN1_LINK#	6	LAN1LINK_LEDPOWER
7	LAN1_ACT#	8	LAN1ACT_LEDPOWER
9	LAN2_LINK#	10	LAN2LINK_LEDPOWER
11	LAN2_ACT#	12	LAN2ACT_LEDPOWER
13	H/W RESET	14	GND

SMBus Pin Header

Connector type: 1x3 3-pin header 2.54mm-M-180
Connector location: JP4



Pin	Definition
1	SMbus_CLK
2	SMbus_data
3	GND

Mic-in Connector

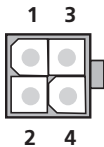
Connector type: 1x4 4-pin header 2.54mm-M-180
Connector location: JP2



Pin	Definition
1	Mic-in L
2	Mic JD
3	GND
4	Mic-in R

Power Output Connector

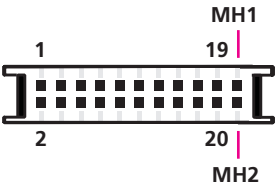
Connector type: 2x2 4-pin AUX 3.5mm
Connector location: CON1



Pin	Definition
1	GND
2	GND
3	VIN Power
4	VIN Power

LVDS Connector

Connector type: 20-pin DF13-20DP 1.25mm
Connector location: CN1



Pin	Definition	Pin	Definition
1	LVDS_DDCCLK	2	LVDS_DDCDATA
3	VCC_LCD(5V Or3.3V)	4	LVDS_A0P
5	NC	6	LVDS_A0N
7	NC	8	VCC_LCD(5V Or3.3V)
9	GND	10	LVDS_A1P
11	LVDS_ACLKP	12	LVDS_A1N
13	LVDS_ACLKN	14	GND
15	GND	16	V_INV (12V)
17	LVDS_A2P	18	V_INV (12V)
19	LVDS_A2N	20	GND

Panel CCFL Connector

Connector type: 1x7 7-pin header JST-2.5mm-M-180
Connector location: J1



Pin	Definition
1	Vcc5
2	V_INV (12V)
3	V_INV (12V)
4	CCFLBKLTCTRL
5	GND
6	GND
7	M_BKLTEN

USB 8-9 Connector

Connector type: 1x6 6-pin JST wafer, 2.5 mm pitch
Connector location: J7

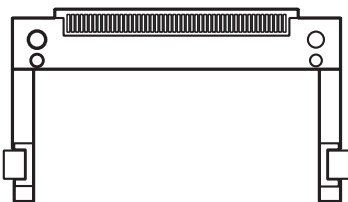


Pin	Definition
1	USB_VCC45
2	USB_8N
3	USB_8P
4	USB_9N
5	USB_9P
6	USB_GND

CompactFlash

Connector type: CompactFlash Type I/II H:6.3mm SMD

Connector location: IDE1

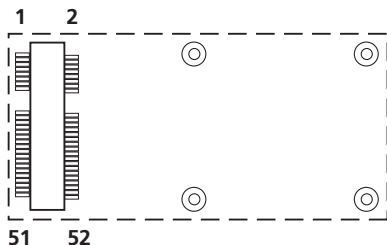


Pin	Description	Pin	Description
1	GND	2	SDD3A
3	SDD4A	4	SDD5A
5	SDD6A	6	SDD7A
7	SDCS#1	8	GND
9	GND	10	GND
11	GND	12	GND
13	VCC	14	GND
15	GND	16	GND
17	GND	18	SDA2A
19	SDA1A	20	SDA0A
21	SDD0A	22	SDD1A
23	SDD2A	24	NC
25	CF_CD2#	26	CF_CD1#
27	SDD11A	28	SDD12A

Pin	Description	Pin	Description
29	SDD13A	30	SDD14A
31	SDD15A	32	SDCS#3
33	NC	34	SDIOR#
35	SDIOW#	36	VCC
37	HDIRQ14	38	VCC
39	CF_SEL#	40	NC
41	IDERST#	42	SIORDY
43	SDREQ	44	SDDACK#
45	IDEACTP#	46	DIAG#
47	SDD8A	48	SDD9A
49	SDD10A	50	GND

Mini-PCle Slot

Connector location: CN5



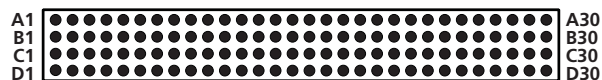
Pin	Definition	Pin	Definition
1	PCIE_WAKE#	2	+V3.3A_MINI
3	NC	4	GND
5	NC	6	+V1.5S_MINI
7	PCIE_MINI_CLKREQ#1	8	SIM_PWER
9	GND	10	SIM_DATA
11	CLK_N	12	SIM_CLK
13	CLK_P	14	SIM_REST
15	GND	16	SIM_VCCP
17	NC	18	GND
19	NC	20	MINICARD1_DIS#
21	GND	22	PCI_RST
23	PCleRX_N	24	+V3.3A_MINI
25	PCleRX_P	26	GND
27	GND	28	+V1.5S_MINI
29	GND	30	SMB_CLK

Pin	Definition	Pin	Definition
31	PCleTX_N	32	SMB_DATA
33	PCleTX_P	34	GND
35	GND	36	USB_DATA_N
37	GND	38	USB_DATA_P
39	+V3.3A_MINI	40	GND
41	+V3.3A_MINI	42	NC
43	GND	44	LED_WLAN_N
45	NC	46	NC
47	NC	48	+V1.5S_MINI
49	NC	50	GND
51	NC	52	+V3.3A_MINI
MH1	GND	MH2	GND
MH3	GND	MH4	GND
MH6	GND		

PCI Slot (Low Profile)

Connector type: 120-pin H:9.6mm 180D GOLD FLASH DIP 5V

Connector location: CN6



Definition					
Pin	A	B	Pin	A	B
1	TRST#	-12V	32	AD16	AD17
2	+12V	TCK	33	+3.3V	C/BE2#
3	TMS	GND	34	FRAME#	GND
4	TDI	TDO	35	GND	IRDY#
5	+5V	+5V	36	TRDY#	+3.3V
6	INTA#	+5V	37	GND	DEVSEL#
7	INTC#	INTB#	38	STOP#	GND
8	+5V	INTD#	39	+3.3V	LOCK#
9	RSV1	PRSENT1#	40	SMBCLK	PERR#
10	+5V	RSV5	41	SMBDAT	+3.3V
11	RSV2	PRSENT2#	42	GND	SERR#
12	GND	GND	43	PAR	+3.3V
13	GND	GND	44	AD15	C/BE1#
14	+3.3Vaux	RSV6	45	+3.3V	AD14
15	RST#	GRPIMD	46	AD13	GND
16	+5V	CLK	47	AD11	AD12
17	GNT#	GND	48	GND	AD10
18	GND	REQ#	49	AD9	GND

19	PME#	+5V	CONNECTOR KEY		
20	AD30	AD31			
21	+3.3V	AD29	52	C/BE0#	AD8
22	AD28	GND	53	+3.3V	AD7
23	AD26	AD27	54	AD6	+3.3V
24	GND	AD25	55	AD4	AD5
25	AD24	+3.3V	56	GND	AD3
26	IDSEL	C/BE3#	57	AD2	GND
27	+3.3V	AD23	58	AD0	AD1
28	AD22	GND	59	+5V	+5V
29	AD20	AD21	60	REQ64#	ACK64#
30	GND	AD19	61	+5V	+5V
31	AD18	+3.3V	62	+5V	+5V

CHAPTER 3: SYSTEM SETUP

Removing the Chassis Cover



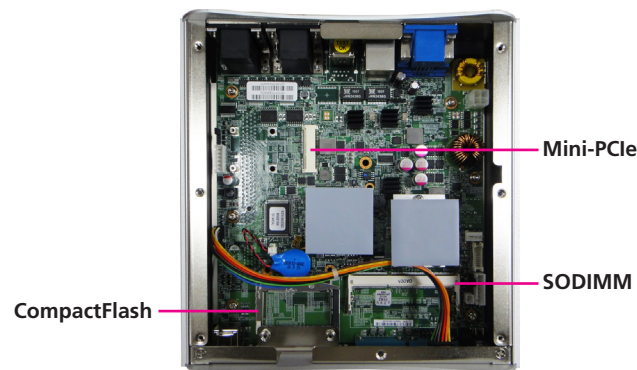
Prior to removing the chassis cover, make sure the unit's power is off and disconnected from the power sources to prevent electric shock or system damage.

1. The screws on the top cover are used to secure the cover to the chassis.
2. Remove these screws and then put them in a safe place for later use.



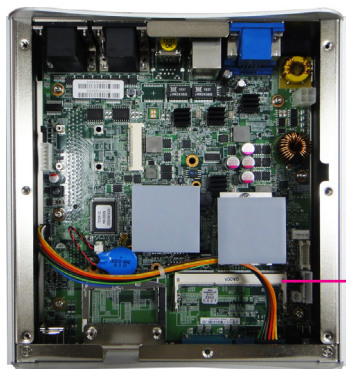
The dots denote the locations of the screws.

3. The SODIMM, Mini-PCle and CompactFlash sockets are readily accessible upon removing the cover.



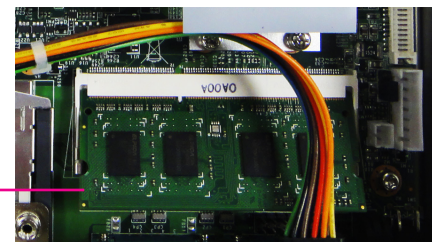
Installing a SODIMM

1. Locate the SODIMM socket on the board.



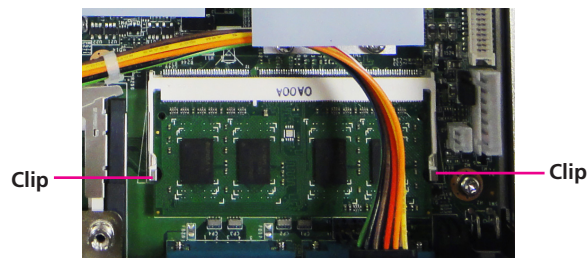
SODIMM
socket

2. Insert the module into the socket at an approximately 30 degrees angle. Apply firm even pressure to each end of the module until it slips into the socket. The gold-plated connector on the edge of the module will almost completely disappear inside the socket.



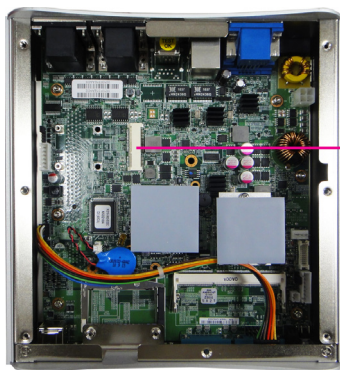
SODIMM

3. Push the module down until the clips on both sides of the socket lock into position. You will hear a distinctive “click”, indicating the module is correctly locked into position.



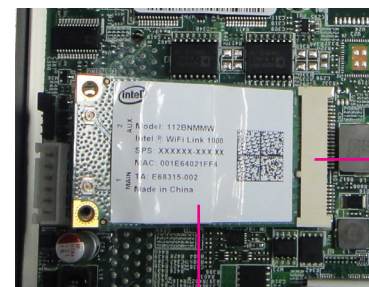
Installing a Wireless LAN Module

1. Locate the Mini PCI Express slot on the board.



Mini PCI Express slot

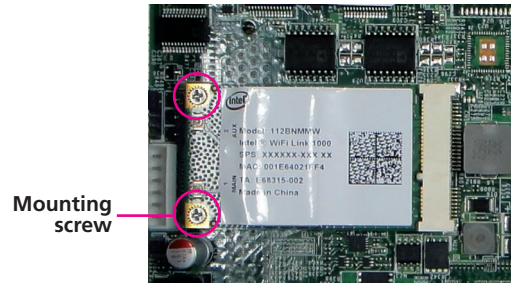
2. Insert the wireless LAN module into the Mini PCI Express slot at a 45 degrees angle until the gold-plated connector on the edge of the module completely disappears inside the slot.



Mini PCI Express slot

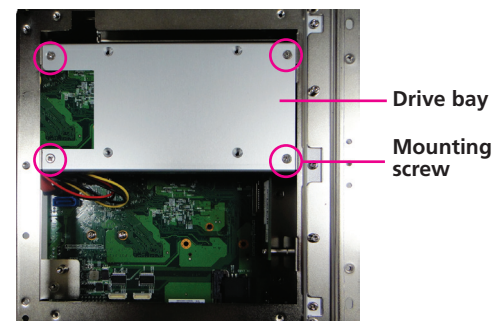
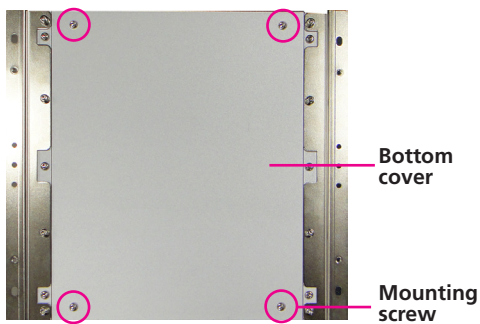
Wireless LAN module

3. Push the module down and then secure it with mounting screws.



Installing a SATA Hard Drive

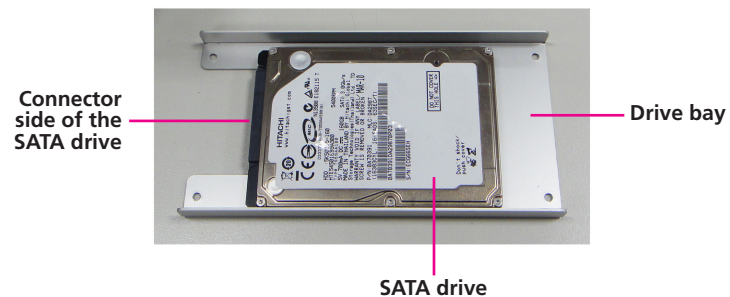
1. With the bottom side of the chassis facing up, remove the mounting screws of the bottom cover and then remove the cover.
2. Remove the 4 mounting screws that secure the drive bay to the chassis and then remove the drive bay.



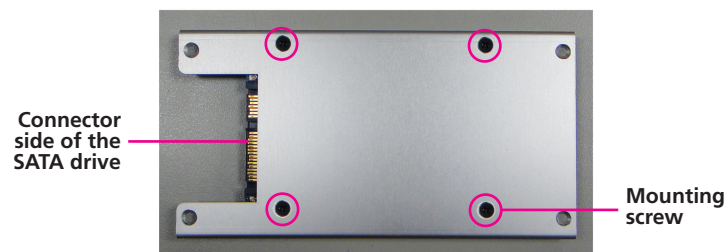
3. The drive bay is used to hold a SATA hard drive.



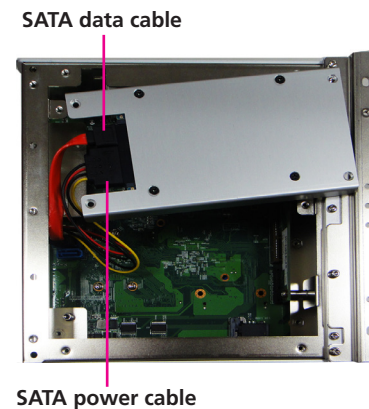
4. Place the SATA hard drive on the drive bay. Align the mounting holes that are on the SATA drive with the mounting holes on the drive bay.



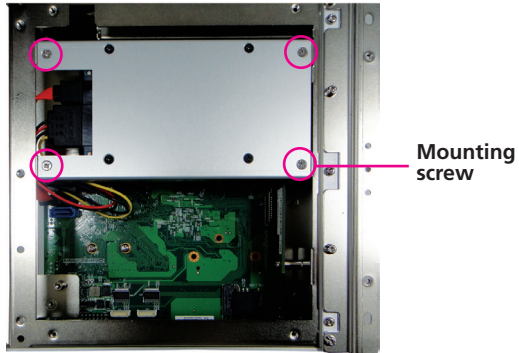
5. Turn to the other side of the bay and then use the provided mounting screws to secure the SATA drive to the drive bay.



6. Connect the SATA data cable and SATA power cable to the connectors on the SATA drive.

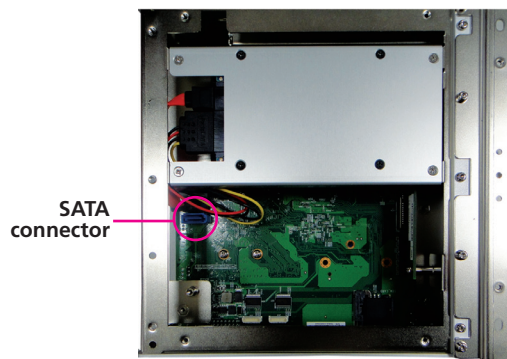


7. Mount the drive bay back into the chassis and then secure it with mounting screws.

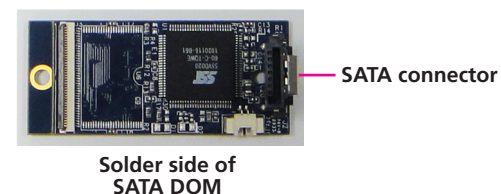
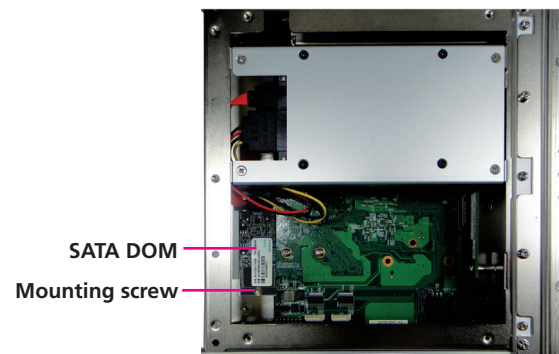


Installing a SATA DOM

1. Locate the SATA connector on the board.



2. Align the SATA connector located on the solder side of the SATA DOM to the SATA connector that is on the board and then press it down firmly. Secure the SATA DOM with the provided mounting screw.

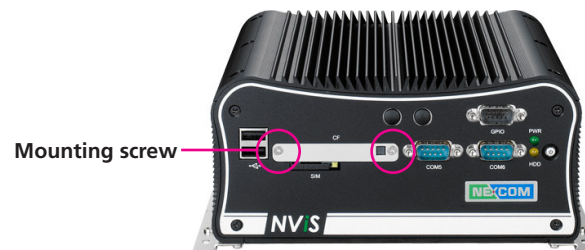


Installing a CompactFlash Card

1. The CompactFlash card must be inserted from the front side of the chassis.
2. Remove the mounting screws of the CompactFlash socket's cover.



CompactFlash
socket cover



3. Remove the socket's cover to access the CompactFlash socket.



CompactFlash
socket

4. With the CompactFlash card's label facing up, insert the card into the socket.



CompactFlash
card

5. Push the eject button to take out the card.



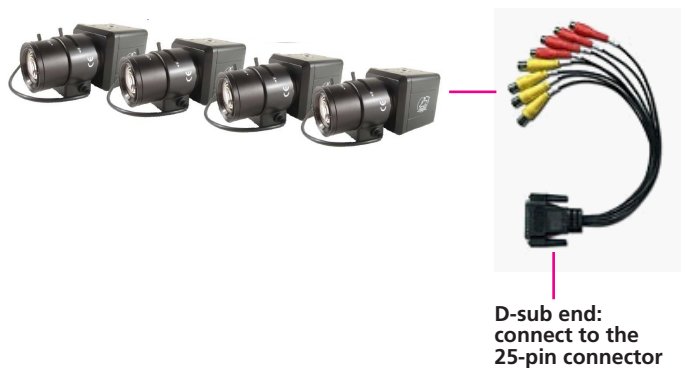
Eject button

Connecting Surveillance Cameras

1. The 25-pin connector on the capture card is used to connect surveillance cameras.



2. Connect the D-sub end of the provided cable to the 25-pin connector and the other ends to surveillance cameras.



CHAPTER 4: BIOS SETUP

This chapter describes how to use the BIOS setup program for the NViS 2140H. The BIOS screens provided in this chapter are for reference only and may change if the BIOS is updated in the future.

To check for the latest updates and revisions, visit the NEXCOM Web site at www.nexcom.com.tw.

About BIOS Setup

The BIOS (Basic Input and Output System) Setup program is a menu driven utility that enables you to make changes to the system configuration and tailor your system to suit your individual work needs. It is a ROM-based configuration utility that displays the system's configuration status and provides you with a tool to set system parameters.

These parameters are stored in non-volatile battery-backed-up CMOS RAM that saves this information even when the power is turned off. When the system is turned back on, the system is configured with the values found in CMOS.

With easy-to-use pull down menus, you can configure such items as:

- Hard drives, diskette drives, and peripherals
- Video display type and display options
- Password protection from unauthorized use
- Power management features

The settings made in the setup program affect how the computer performs. It is important, therefore, first to try to understand all the Setup options, and second, to make settings appropriate for the way you use the computer.

When to Configure the BIOS

This program should be executed under the following conditions:

- When changing the system configuration
- When a configuration error is detected by the system and you are prompted to make changes to the Setup program
- When resetting the system clock
- When redefining the communication ports to prevent any conflicts
- When making changes to the Power Management configuration
- When changing the password or making other changes to the security setup

Normally, CMOS setup is needed when the system hardware is not consistent with the information contained in the CMOS RAM, whenever the CMOS RAM has lost power, or the system features need to be changed.

Default Configuration

Most of the configuration settings are either predefined according to the Load Optimal Defaults settings which are stored in the BIOS or are automatically detected and configured without requiring any actions. There are a few settings that you may need to change depending on your system configuration.

Entering Setup

When the system is powered on, the BIOS will enter the Power-On Self Test (POST) routines. These routines perform various diagnostic checks; if an error is encountered, the error will be reported in one of two different ways:

- If the error occurs before the display device is initialized, a series of beeps will be transmitted.
- If the error occurs after the display device is initialized, the screen will display the error message.

Powering on the computer and immediately pressing allows you to enter Setup. Another way to enter Setup is to power on the computer and wait for the following message during the POST:

```
TO ENTER SETUP BEFORE BOOT
PRESS <CTRL-ALT-ESC>
Press the <Del> key to enter Setup:
```

Legends

Key	Function
Right and Left arrows	Moves the highlight left or right to select a menu.
Up and Down arrows	Moves the highlight up or down between sub-menus or fields.
<Esc>	Exits to the BIOS Setup Utility.
+ (plus key)	Scrolls forward through the values or options of the highlighted field.
- (minus key)	Scrolls backward through the values or options of the highlighted field.
Tab	Selects a field.
<F1>	Displays General Help.
<F10>	Saves and exits the Setup program.
<Enter>	Press <Enter> to enter the highlighted sub-menu.

Scroll Bar

When a scroll bar appears to the right of the setup screen, it indicates that there are more available fields not shown on the screen. Use the up and down arrow keys to scroll through all the available fields.

Submenu

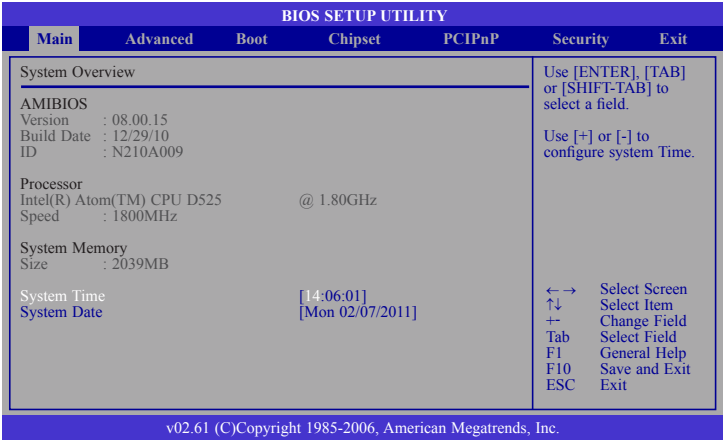
When “►” appears on the left of a particular field, it indicates that a submenu which contains additional options are available for that field. To display the submenu, move the highlight to that field and press <Enter>.

BIOS Setup Utility

Once you enter the AMI BIOS Setup Utility, the Main Menu will appear on the screen. The main menu allows you to select from six setup functions and one exit choices. Use arrow keys to select among the items and press <Enter> to accept or enter the submenu.

Main

The Main menu is the first screen that you will see when you enter the BIOS Setup Utility.



AMI BIOS

Displays the detected BIOS information.

Processor

Displays the detected processor information.

System Memory

Displays the detected system memory information.

System Time

The time format is <hour>, <minute>, <second>. The time is based on the 24-hour military-time clock. For example, 1 p.m. is 13:00:00. Hour displays hours from 00 to 23. Minute displays minutes from 00 to 59. Second displays seconds from 00 to 59.

System Date

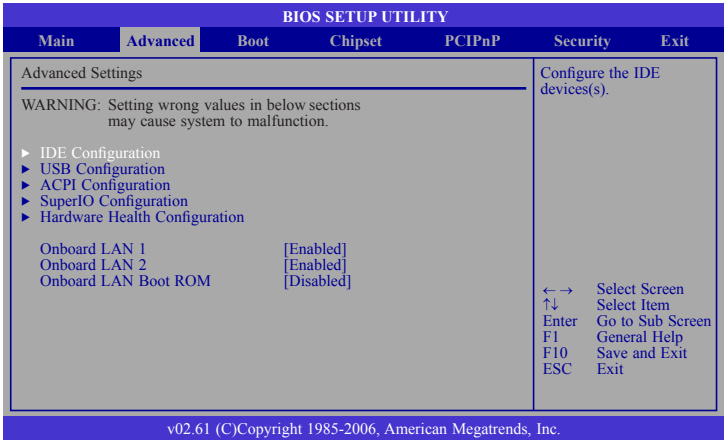
The date format is <day>, <month>, <date>, <year>. Day displays a day, from Sunday to Saturday. Month displays the month, from January to December. Date displays the date, from 1 to 31. Year displays the year, from 1999 to 2099.

Advanced

The Advanced menu allows you to configure your system for basic operation. Some entries are defaults required by the system board, while others, if enabled, will improve the performance of your system or let you set some features according to your preference.



Setting incorrect field values may cause the system to malfunction.



IDE Configuration

This section is used to configure the IDE drives.

USB Configuration

This section is used to configure USB devices.

ACPI Configuration

This section is used to configure the Advanced ACPI configuration.

Super IO Configuration

This section is used to configure the I/O functions supported by the on-board Super I/O chip.

Hardware Health Configuration

This section is used to configure the hardware monitoring events such as temperature, fan speed and voltages.

Onboard LAN 1 and Onboard LAN 2

This section is used to enable or disable the onboard LAN.

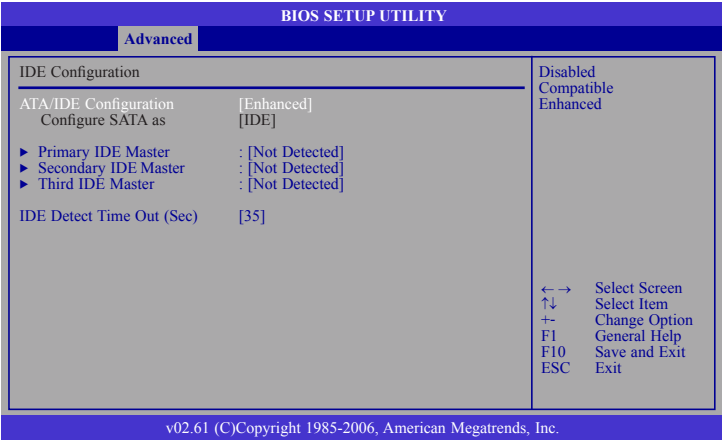
Onboard LAN Boot ROM

Enable this field if you wish to use the boot ROM (instead of a disk drive) to boot-up the system and access the local area network directly.

If you wish to change the boot ROM's settings, type the <Shift> and <F10> keys simultaneously when prompted during boot-up. Take note: you will be able to access the boot ROM's program (by typing <Shift> + <F10>) only when this field is enabled.

IDE Configuration

This section is used to configure the IDE drives.



ATA/IDE Configuration

This field is used to configure the IDE drives. The options are Disabled, Compatible and Enhanced.

Configure SATA As

- IDE This option configures the Serial ATA drives as Parallel ATA physical storage device.
- AHCI This option configures the Serial ATA drives to use AHCI (Advanced Host Controller Interface). AHCI allows the storage driver to enable the advanced Serial ATA features which will increase storage performance.

Primary IDE Master to Third IDE Master

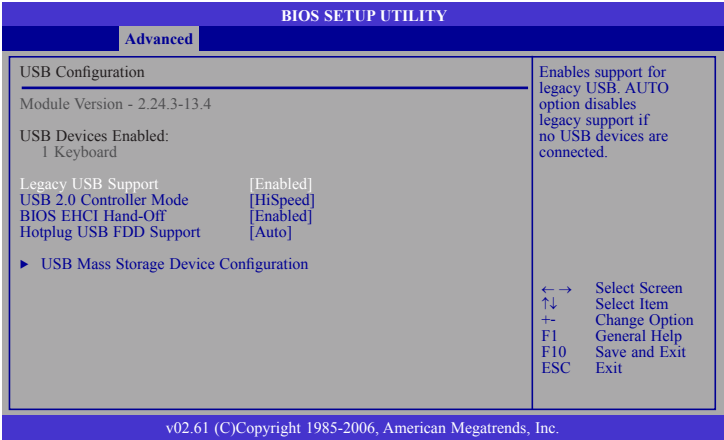
When you enter the BIOS Setup Utility, the BIOS will auto detect the existing IDE devices then displays the status of the detected devices. To configure an IDE drive, move the cursor to a field then press <Enter>.

IDE Detect Time Out (Sec)

Selects the time out value for detecting ATA/ATAPI devices.

USB Configuration

This section is used to configure USB devices.



Legacy USB Support

Due to the limited space of the BIOS ROM, the support for legacy USB keyboard (in DOS mode) is by default set to Disabled. With more BIOS ROM space available, it will be able to support more advanced features as well as provide compatibility to a wide variety of peripheral devices.

If a PS/2 keyboard is not available and you need to use a USB keyboard to install Windows (installation is performed in DOS mode) or run any program under DOS, set this field to Enabled.

USB 2.0 Controller Mode

Sets the USB 2.0 controller mode to HiSpeed (480 Mbps) or FullSpeed (12 Mbps).

BIOS EHCI Hand-Off

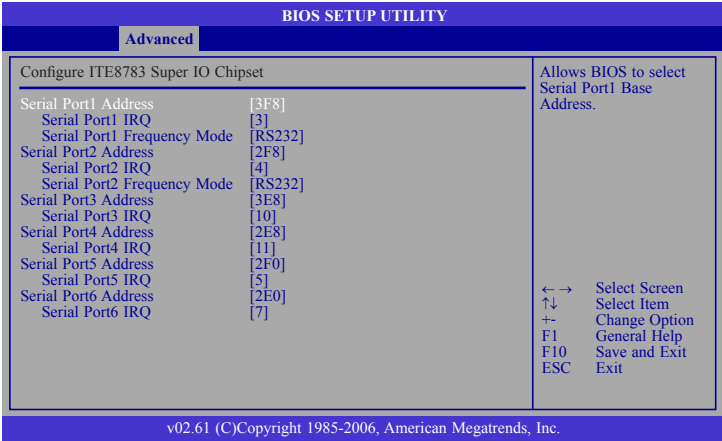
Enable this field when using operating systems without the EHCI hand-off support.

Hotplug USB FDD Support

Enables support for USB FDD hot plug.

Super IO Configuration

This section is used to configure the I/O functions supported by the on-board Super I/O chip.



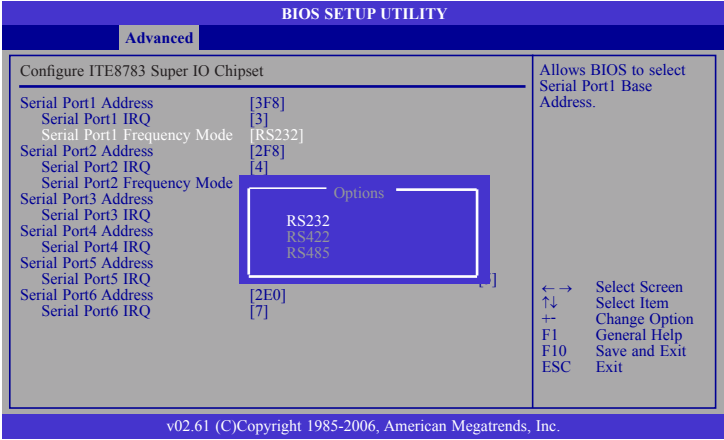
Serial Port1 Address to Serial Port6 Address

- Auto The system will automatically select an I/O address for the on-board serial port.
- 3F8, 2F8, 3E8, 2E8, 2F0, 2E0 Allows you to manually select an I/O address for the onboard serial port.
- Disabled Disables the onboard serial port.

Serial Port1 IRQ to Serial Port6 IRQ

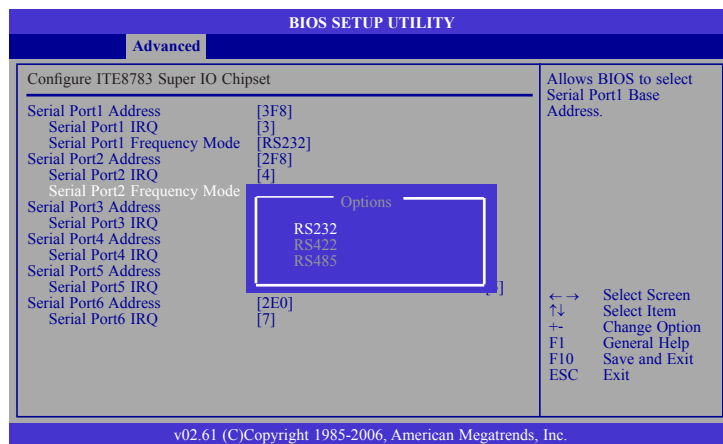
These fields are used to select an IRQ for the onboard serial port 1, 2, 3, 4, 5 or 6.

Serial Port1 Frequency Mode



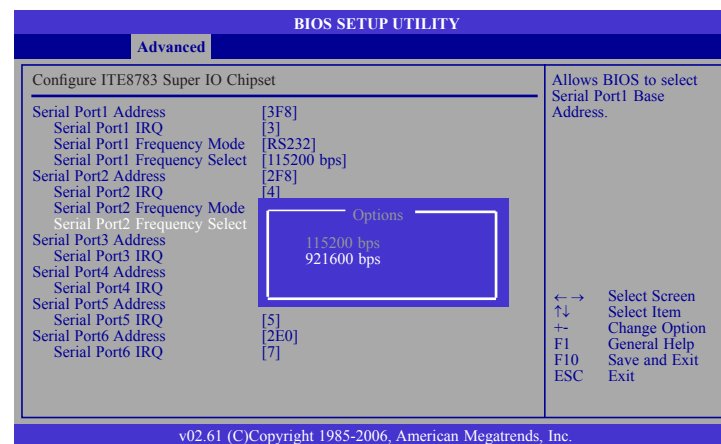
This field is used to select the frequency mode of serial port 1. The options are RS232, RS422 and RS485.

Serial Port2 Frequency Mode



This field is used to select the frequency mode of serial port 2. The options are RS232, RS422 and RS485.

If you selected RS422 or RS485 in the “Serial Port1 Frequency Mode” and/or “Serial Port2 Frequency Mode” field, the “Serial Port1 Frequency Select” and/or “Serial Port2 Frequency Select” field will appear prompting you to select the frequency setting. The options are 115200 bps and 921600 bps.

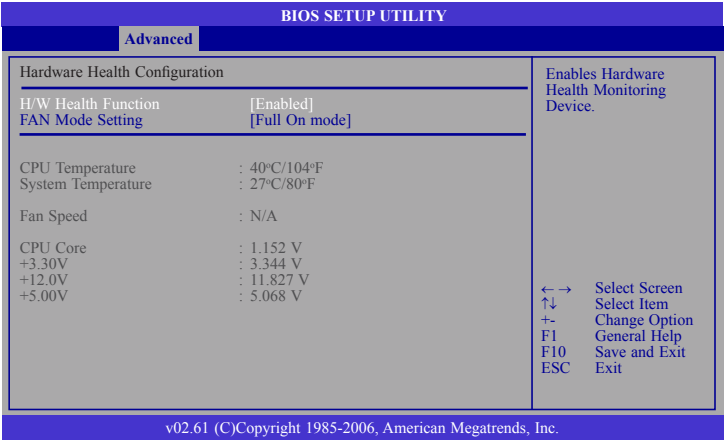


Hardware Health Configuration

This section is used to configure the hardware monitoring events such as temperature, fan speed and voltages.

CPU Core to +5.00V

Detects and displays the output voltages.



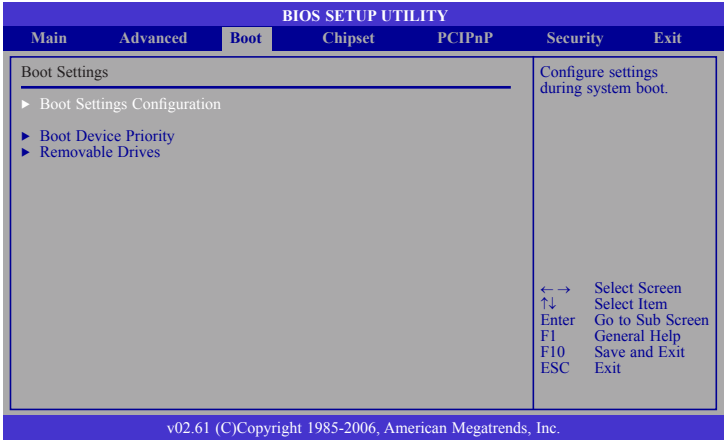
H/W Health Function

Enables or disables the hardware monitoring function.

CPU Temperature and System Temperature

Detects and displays the current temperature of the CPU and the internal temperature of the system.

Boot



Boot Settings Configuration

This section is used to configure settings during system boot.

Boot Device Priority

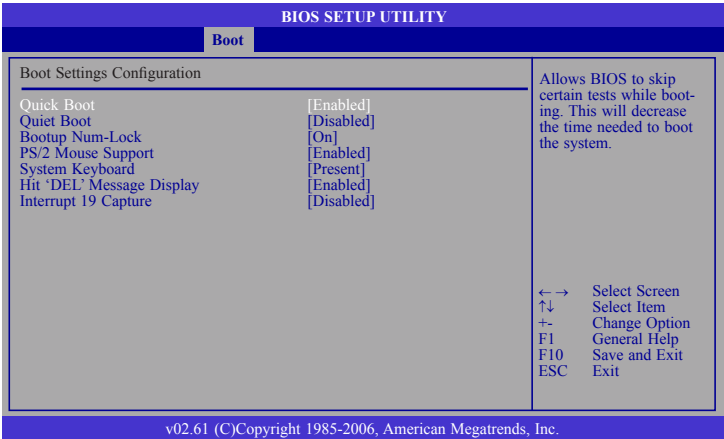
This section is used to select the boot priority sequence of the devices.

Removable Drives

This section is used to select the boot priority sequence of the removable drives.

Boot Settings Configuration

This section is used to configure settings during system boot.



Quick Boot

When Enabled, the BIOS will shorten or skip some check items during POST. This will decrease the time needed to boot the system.

Quiet Boot

Enabled Displays OEM logo instead of the POST messages.
Disabled Displays normal POST messages.



Bootup Num-Lock

This allows you to determine the default state of the numeric keypad. By default, the system boots up with NumLock on wherein the function of the numeric keypad is the number keys. When set to Off, the function of the numeric keypad is the arrow keys.

PS/2 Mouse Support

The options are Auto, Enabled and Disabled.

System Keyboard

Detects the system keyboard.

Hit ‘DEL’ Message Display

When enabled, the system displays the “Press DEL to run Setup” message during POST.

Interrupt 19 Capture

When enabled, it allows the optional ROM to trap interrupt 19.

Boot Device Priority

This section is used to select the boot priority sequence of the devices.

BIOS SETUP UTILITY

Boot

Boot Device Priority

1st Boot Device [USB:JetFlash Trans]
2nd Boot Device
3rd Boot Device

Specifies the boot sequence from the available devices.

A device enclosed in parenthesis has been disabled in the corresponding type menu.

← → Select Screen
↑ ↓ Select Item
+ - Change Option
F1 General Help
F10 Save and Exit
ESC Exit

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1st Boot Device to 3rd Boot Device

Selects the drive to boot first, second and third in the “1st Boot Device”, “2nd Boot Device” and “3rd Boot Device” fields respectively. The BIOS will boot the operating system according to the sequence of the drive selected.

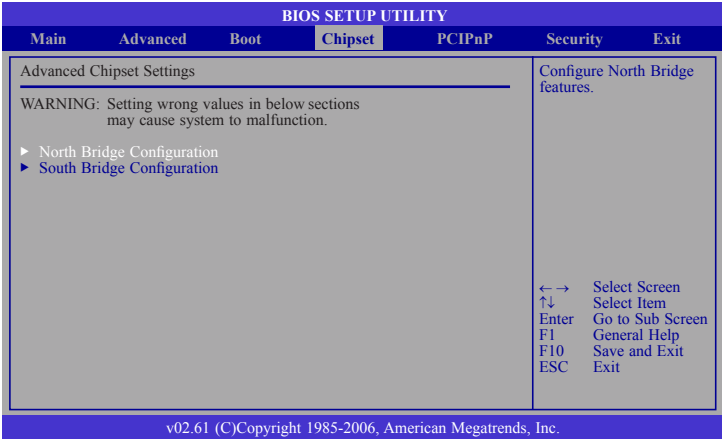


Chipset

This section is used to configure the system based on the specific features of the chipset.

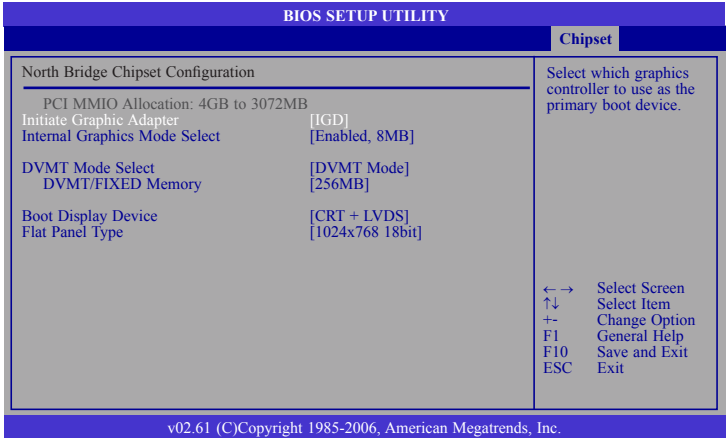


Setting incorrect field values may cause the system to malfunction.



North Bridge Configuration

This section is used to configure the north bridge features.



Initiate Graphic Adapter

Selects the graphics controller to use as the primary boot device.

Internal Graphics Mode Select

Selects the amount of system memory used by the internal graphics device.

DVMT Mode Select

The options are Fixed mode and DVMT mode.

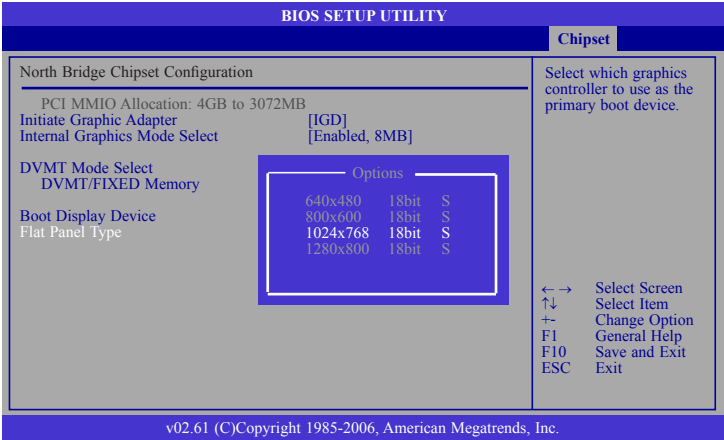
DVMT/Fixed Memory

This field is used to select the graphics memory size used by DVMT/Fixed mode.

Boot Display Device

This field is used to select the type of display to use when the system boots.

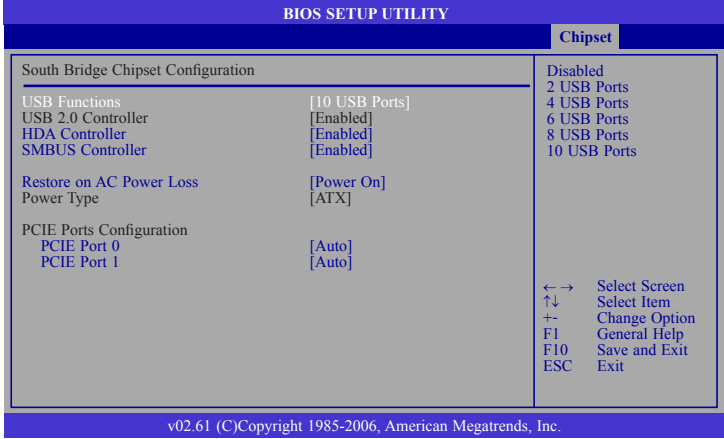
Flat Panel Type



Selects the type of flat panel connected to the system. The supported LVDS are 640x480 18bit, 800x600 18bit, 1024x768 18bit and 1280x800 18bit.

South Bridge Configuration

This section is used to configure the south bridge features.



USB Functions

Enables or disables USB devices.

USB 2.0 Controller

This field is used to enable or disable the Enhanced Host Controller Interface (USB 2.0).

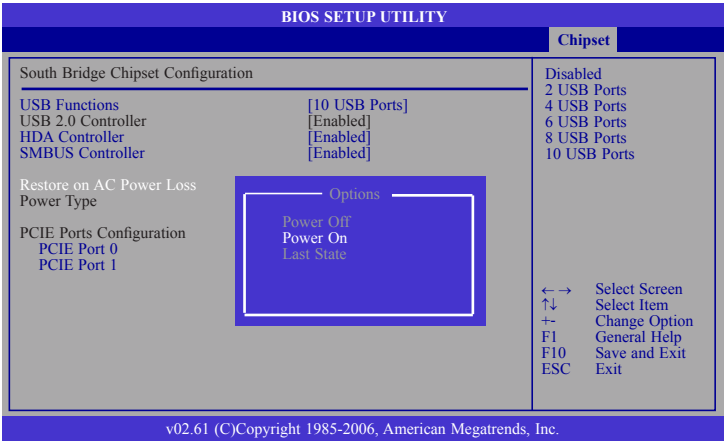
HDA Controller

Enables or disables the onboard audio.

SMBUS Controller

Enables or disables the SMBUS.

Restore On AC Power Loss



- Power Off When power returns after an AC power failure, the system's power is off. You must press the Power button to power-on the system.
- Power On When power returns after an AC power failure, the system will automatically power-on.
- Last State When power returns after an AC power failure, the system will return to the state where you left off before power failure occurs. If the system's power is off when AC power failure occurs, it will remain off when power returns. If the system's power is on when AC power failure occurs, the system will power-on when power returns.

Power Type


Selects the type of power used.

PCIE Port 0 and PCIE port 1

Configures the PCIE ports.

PCIPnP

This section is used to configure settings for PCI/PnP devices.



Setting incorrect field values may cause the system to malfunction.

PCI Latency Timer

This feature is used to select the length of time each PCI device will control the bus before another takes over. The larger the value, the longer the PCI device can retain control of the bus. Since each access to the bus comes with an initial delay before any transaction can be made, low values for the PCI Latency Timer will reduce the effectiveness of the PCI bandwidth while higher values will improve it.

IRQ3 to IRQ15

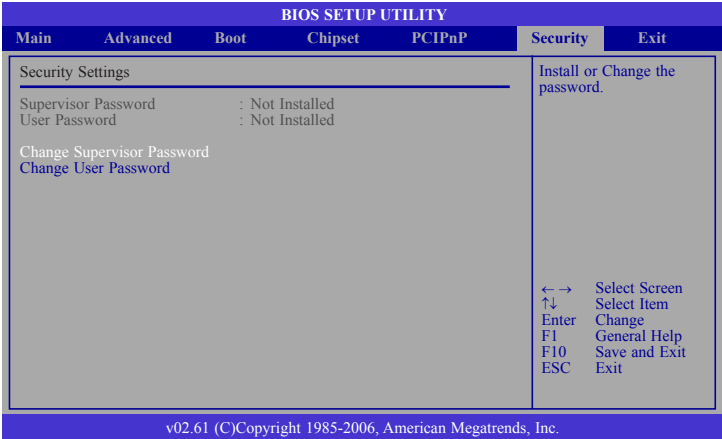
- Available
- The specified IRQ is available for PCI/PnP devices.
- Reserved
- The specified IRQ is reserved for Legacy ISA devices.

BIOS SETUP UTILITY						
Main	Advanced	Boot	Chipset	PCIPnP	Security	Exit
Advanced PCI/PnP Settings					NO: let the BIOS configure all the devices in the system. YES: lets the operating system configure Plug and Play (PnP) devices not required for boot if your system has a Plug and Play operating system. ← → Select Screen ↑↓ Select Item +~ Change Option F1 General Help F10 Save and Exit ESC Exit	
WARNING: Setting wrong values in below sections may cause system to malfunction.						
Plug & Play O/S		[No]				
PCI Latency Timer		[64]				
IRQ3		[Available]				
IRQ4		[Available]				
IRQ5		[Available]				
IRQ7		[Available]				
IRQ9		[Available]				
IRQ10		[Available]				
IRQ11		[Available]				
IRQ14		[Available]				
IRQ15		[Available]				
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Plug & Play O/S

- Yes
- Configures Plug and Play (PnP) devices that are not required to boot in a Plug and Play supported operating system.
- No
- The BIOS configures all the devices in the system.

Security



Change Supervisor Password

This field is used to set or change the supervisor password.

To set a new password:

1. Select the Change Supervisor Password field then press <Enter>.
2. Type your password in the dialog box then press <Enter>. You are limited to eight letters/numbers.
3. Press <Enter> to confirm the new password.
4. When the Password Installed dialog box appears, select OK.

To change the password, repeat the same steps above.

To clear the password, select Change Supervisor Password then press <Enter>. The Password Uninstalled dialog box will appear.

If you forgot the password, you can clear the password by erasing the CMOS RTC (Real Time Clock) RAM using the RTC Clear jumper. Refer to chapter 2 for more information.

Change User Password

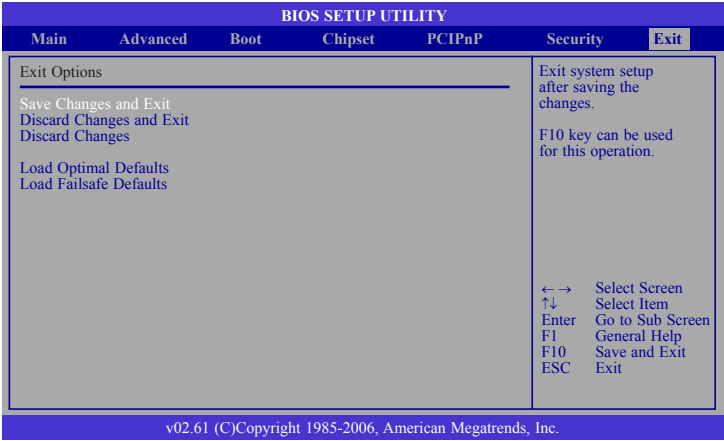
This field is used to set or change the user password.

To set a new password:

1. Select the Change User Password field then press <Enter>.
2. Type your password in the dialog box then press <Enter>. You are limited to eight letters/numbers.
3. Press <Enter> to confirm the new password.
4. When the Password Installed dialog box appears, select OK.

To change the password, repeat the same steps above.

Exit



Save Changes and Exit

To save the changes and exit the Setup utility, select this field then press <Enter>. A dialog box will appear. Confirm by selecting Yes. You can also press <F10> to save and exit Setup.

Discard Changes and Exit

To exit the Setup utility without saving the changes, select this field then press <Enter>. You may be prompted to confirm again before exiting. You can also press <ESC> to exit without saving the changes.

Discard Changes

To discard the changes, select this field then press <Enter>. A dialog box will appear. Confirm by selecting Yes to discard all changes made and restore the previously saved settings.

Load Optimal Defaults

Loads the optimal default values from the BIOS ROM.

Load Failsafe Defaults

Loads the fail-safe default values from the BIOS ROM.

CHAPTER 5: HUPERVISION SOFTWARE INSTALLATION

Installing huperVision

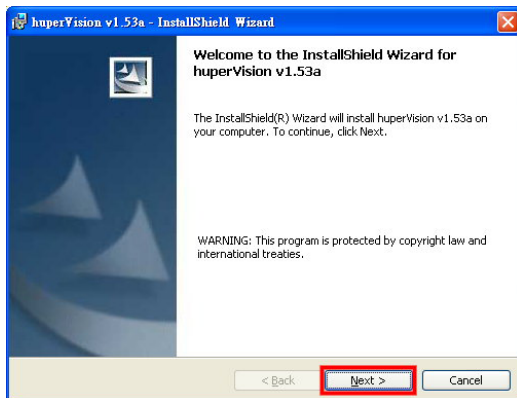
1. Insert the provided CD into a CD-ROM drive.
2. The following autorun screen will appear. Click **huperVision**.



3. Select the language for this installation and then click **OK**.



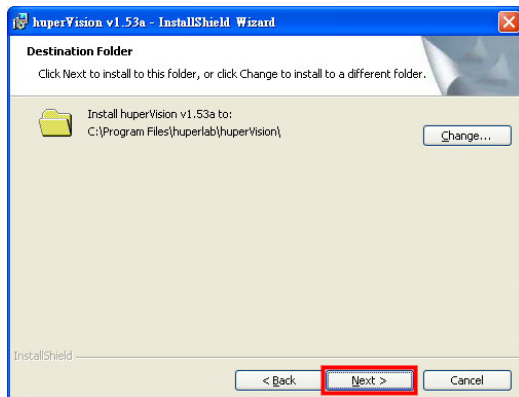
4. Click **Next** to start installing the program.



5. Read the License Agreement and then click **I accept the terms in the license agreement**. Click **Next**.



6. Click **Next** to install to the default folder or click **Change** to install to a different folder.

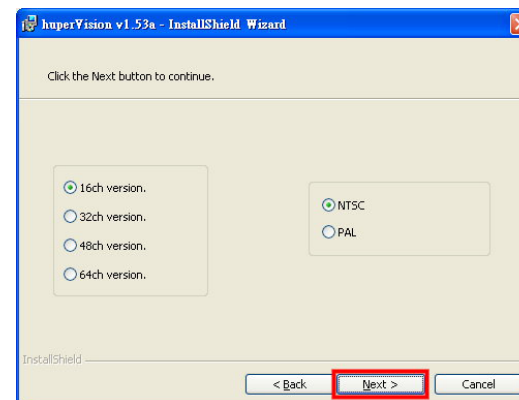


7. Select the channel version.

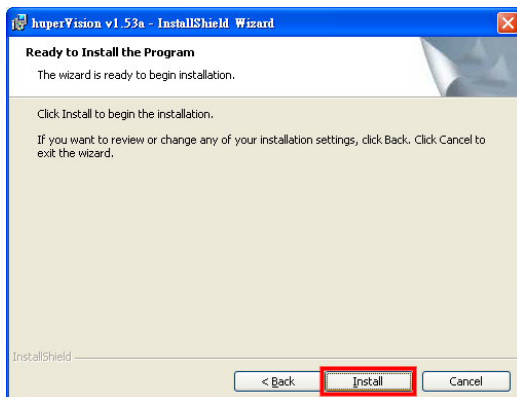
Select **16ch version** to fit all huperVision series capture cards.

To setup a 32ch machine, select 32ch version which will use dual VGA output.

Select the video standard, **NTSC or PAL**, and then click **Next**. (You can later change this option after setup).



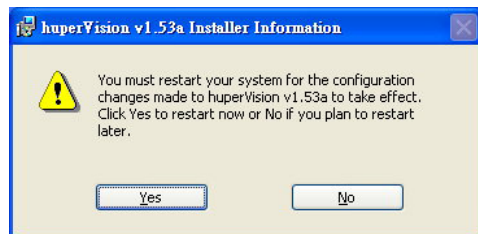
8. Now click **Install** to begin the installation.



9. Click **Finish**.



10. You must restart your system for the configuration changes made to hyperVision to take effect. Click **Yes** to restart the system.

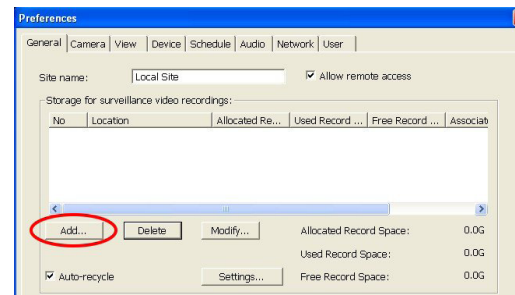


Start Recording

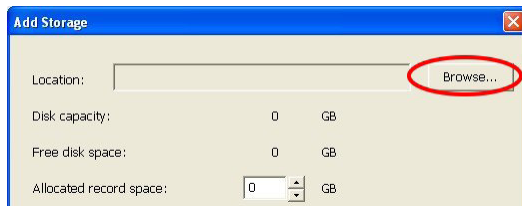
1. When the system reboots, a message will appear reminding you to specify the recording path of the cameras. Click **OK**.
2. Click the **Hammer** button  and then select **Preferences**.
3. Click **Add** to create a new folder that you want to store the recorded data files to.



2. Click the **Hammer** button  and then select **Preferences**.



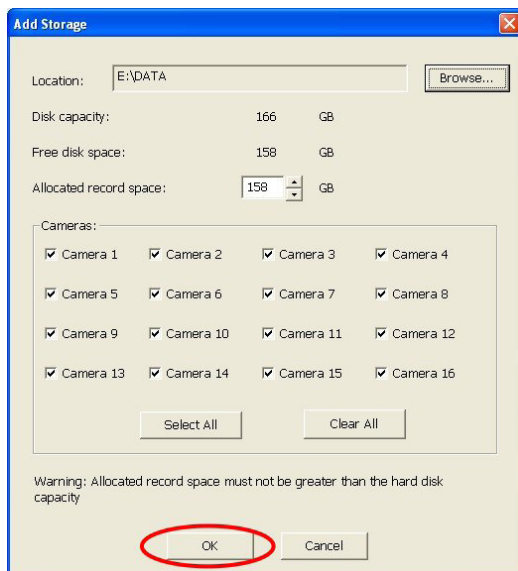
4. In the Add Storage dialog box, click **Browse** to display the Navigation pane.



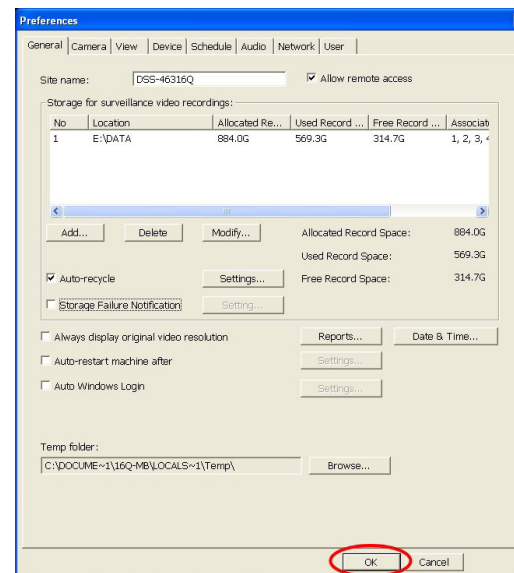
5. Click the drive that you want to save the files to and then click **Make New Folder**. Type a name for the folder in the **Folder** box, and then click **OK**.



6. After setting the storage location, you will return to the Add Storage dialog box. Click **OK** to save.



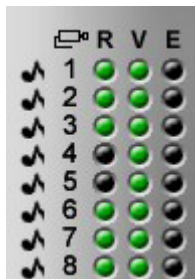
7. In the Preferences dialog box, click **OK**. You can start recording videos.




Keep all 16 cameras selected even if you don't have that much cameras.

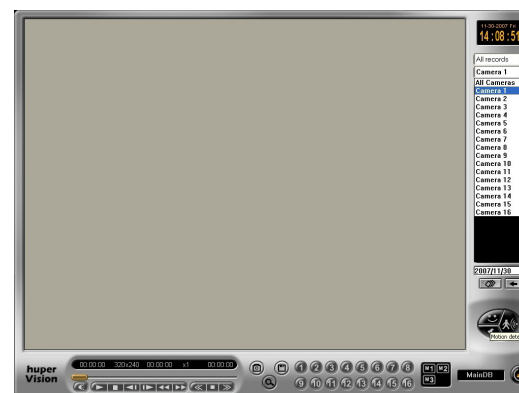
Do not change the default value of the Allocated record space.

8. The **R LEDs** at the upper right side will turn green. This indicates that available channels are currently recording.



Playback Recordings

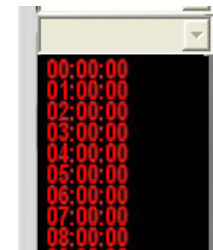
1. Click this icon  to run the huperVision Record Player program.
2. **Record Player** (as shown below) will appear while Live View and recording task continue to run on the background.



3. Select a playback channel from the camera list or click All Cameras to playback all the available channels at the same time.




4. After you have selected the channels, a list of time mark for today's recording will appear. Select a **time mark** to load the recorded videos.



5. All the video channels will show the first image in the Video split area. After the video has loaded (progress bar reached the end), press the **Play** button to start playing the selected recording.



6. To select another channel, repeat steps 3 to 5.
7. Click the **Power Off** button  to exit the playback program.



Pressing the Power button will NOT immediately close the hyperVision site server. You are protected from accidentally pressing the Power button as a Confirm dialog box will appear whenever the Power button is pressed. You have to confirm that you want to close the program before the hyperVision site server main program actually shuts down.

8. You are now ready to use the hyperVision IVS system. To view the Users Manual for more information on Intelligent Video Functions, click **Documents** on the installation CDROM's autorun program.



The document will open using **Acrobat Reader**. If you don't have Acrobat Reader installed in your computer yet, you must install the Reader first to be able to view the document. Acrobat Reader is available in the installation CDROM. *E:\English\Doc\aar.exe*

Connecting IP Cameras / Video Servers

1. To use IP cameras as video source for recording and intelligent analysis, click **IP Camera Plugin** on the installation CDROM's autorun program.

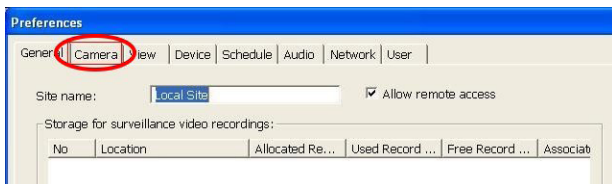


You will now be able to use all IP camera related features.

2. Click the **Hammer** button  and then select **Preferences**.



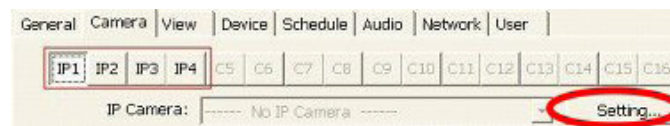
3. Click the **Camera** tab to start connecting IP cameras.



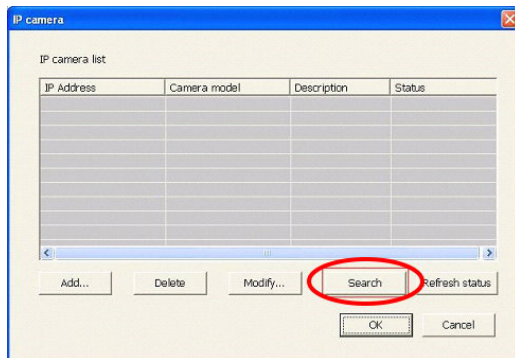
4. When you have Hybrid License card or Pure IP license card installed, the Camera setting page will show **IP1**, **IP2**, **IP3** instead of C1, C2, C3 to differentiate 2 different Camera types.



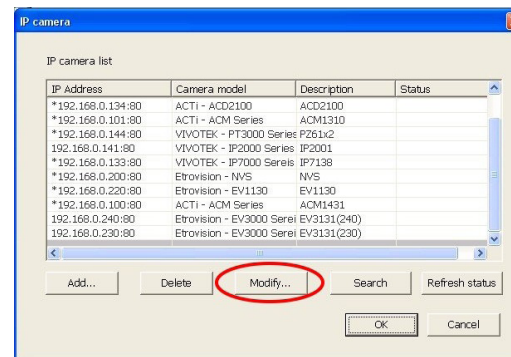
5. Select **IP1** and then select **Setting**.



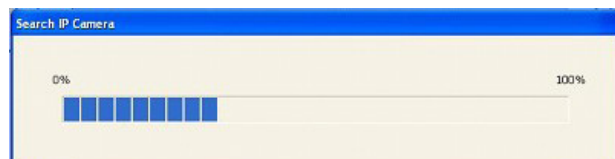
6. The IP Camera dialog box will appear. Click **Search**.



8. If you want to change the setting of an IP camera, e.g. ID/PW connection, select the IP camera and then click **Modify**.



7. It will take a few minutes to search all the supported IP cameras in the local network range. Wait till the progress bar reached the end.



9. After entering the necessary information, click **OK** to save the settings.

Modify

Network setting
 IP address: 192.168.0.220
 HTTP Port: 80

Account setting
 Account:
 Password:
☐ Anonymous

Camera information
 Camera model: Etrvision - EV1130
 Description:

Advance setting:
 Connect...

OK Cancel

10. Click **OK** to complete the connection setting.

IP camera

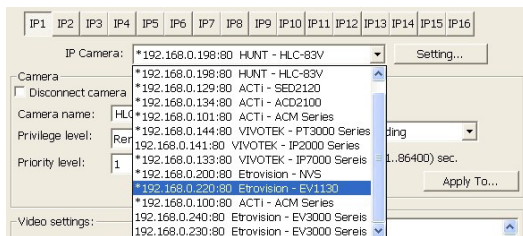
IP camera list


IP Address	Camera model	Description	Status
*192.168.0.134:80	ACTi - ACD2100	ACD2100	
*192.168.0.101:80	ACTi - ACM Series	ACM1310	
*192.168.0.144:80	VIVOTEK - PT3000 Series	P261x2	
192.168.0.141:80	VIVOTEK - IP2000 Series	IP2001	
*192.168.0.133:80	VIVOTEK - IP7000 Series	IP7138	
*192.168.0.200:80	Etrvision - NVS	NVS	
*192.168.0.220:80	Etrvision - EV1130	EV1130	
*192.168.0.100:80	ACTi - ACM Series	ACM1431	
192.168.0.240:80	Etrvision - EV3000 Series	EV3131(240)	
192.168.0.230:80	Etrvision - EV3000 Series	EV3131(230)	

Add... Delete Modify... Search Refresh status

OK Cancel

11. Under IP Camera, in the drop-down list, select the IP camera for IP1 connection.



 IP Cameras with asterisk before it indicate that these cameras have been assigned in the hyperVision system already.

hyperVision system allows you to do multiple connection to one IP camera for different purposes but note that all IP cameras have their connection limitations or bandwidth limitations. Overloading a single IP Camera / Video Server may cause unexpected result.

12. Click **OK** to save the settings. It will take a few seconds to connect before you see the video.

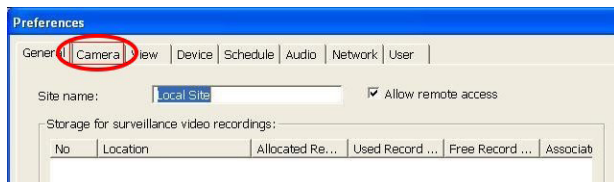
Using Motion Detection

Motion Detection is the basic detection function of hyperVision. It works like a motion sensor but with more powerful parameters to control the precision of the detection result.

2. Click the **Hammer** button  and then select **Preferences**.



2. Click the **Camera** tab to bring up all the camera settings.

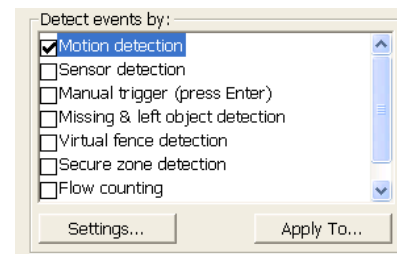


3. Click **C1~16** or **IP1~16** of the camera you want to apply the motion detection.

e.g. C4 is for the 4th camera and it is an Analog camera; IP6 is for the 6th camera and it is an IP camera or Video server.



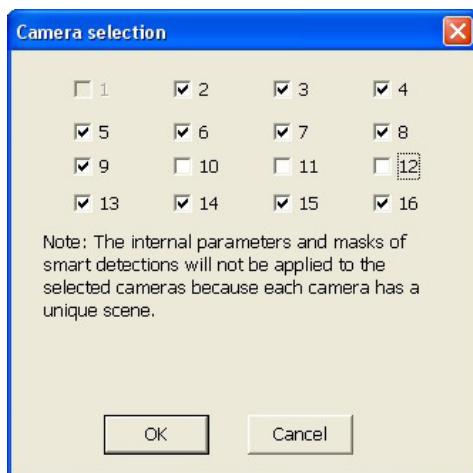
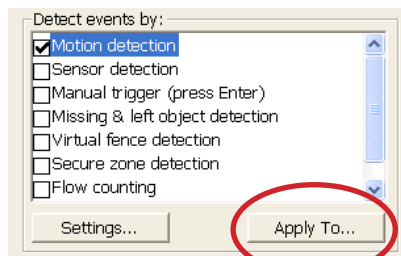
4. All Motion Detection features are under the **Detect events by** list.



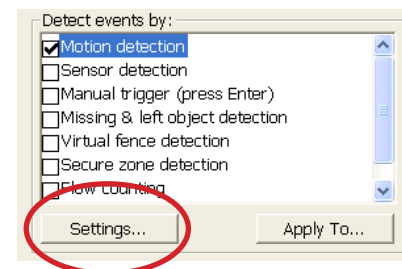
5. Click the feature and then click **OK**.

- Click **Apply To** to select the cameras you want their Motion Detection feature enabled.

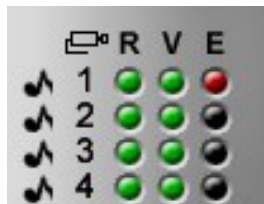
If you de-selected 10~12, Motion Detection will apply to all cameras except No. 10, 11 and 12.



- Click **Settings** to bring up the detailed Motion Detection settings like Adjustment of Sensitivity and Noise Tolerance, Ignore Smaller or Larger objects and mask out some area which you don't want the motions detected. For details on Motion Detection settings, refer to the users manual.



8. On huperVision's main screen, the upper right corner shows a list of LED indicators. When a motion has been detected by a camera, the LED under "E" will turn Red.



Ignoring Smaller/Larger Object Size During Detection

Ignore Smaller Object and Ignore Larger Object functions are available in most huperVision's detection settings. Ignore smaller objects like mice, cockroaches or smaller animals if you want to detect and alarm humans or vehicles. Ignore larger objects like a hand over camera lenses or camera shaking situation. Both size filter settings can improve a better alarm precision when proper value is applied.

1. Click this function to enable **Ignore Smaller Objects**. You can either adjust the value based on the object's width and height counted by pixel, or you can click the hand icon to use your mouse to drag the size directly on the video. When done, click the hand icon again to stop the selection.




- Click this function to enable **Ignore Larger Objects**. It works in the same way as the ignore smaller objects. Note that if your ignore smaller size is larger than ignore larger size, you know that it's not logical and will not work.



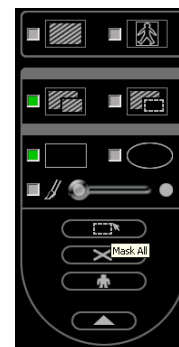
- Note that when you selected the hand icon, the only thing you can do is use your mouse to drag the size of the object on the video. You cannot do anything else when this button is pressed again.

Masking in Detection Features

The **Mask** feature exists in some detection features such as “Motion Detection” and “Missing & Left Object Detection”. You can either set a full Video detection or mask out some unwanted area to prevent false alarms.

- Let's take Motion Detection as an example. When you open the **Motion Detection** settings page, click the drop-down button  to extend the **Mask** menu.

You are now ready to perform a mask on the video.

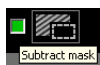


2. There are 2 types of masks that can be applied:

Add Mask



Subtract Mask



Add Mask allows you to block out some areas of the detection while **Subtract Mask** helps you recover some areas of the detection from Mask. Combine both kind of Mask and you can easily perform a complicated mask to form a precise detection area.

There are 3 types of Mask shapes that you can use when doing Add Mask and Subtract Mask:

Rectangle Shape







Circular Shape



Free Hand Sketching



The steps below is an example of performing Add Mask and Subtract Mask.

1. Click the **Add Mask** mode. 
2. Click the **Rectangle Shape**. 
3. Use your mouse to drag the **Rectangle Shape** to block out the Flashing screen from Motion Detection.
4. Click the **Circular Shape**. 
5. Drag the **Circular Shape** over the Video. You will notice that the overlapped area between the circle and rectangle will auto-merge together.
6. Click the **Free Hand Sketching**. 
 Dragging the size control bar to the right will let you draw with a bigger pen tip.
7. Click and hold to draw mask area on the video.

8. You will see the masked area as shown in the picture below. The masked area is marked in green color, which means you don't want these areas detected.



Full Screen Mask



When you need to block out most of the areas and only want to detect some areas, you can use this button to block out the entire video and the system will auto switch to Subtract Mask mode and let you remove some Mask areas.



1. Click the **Mask All** button.



You will notice that the entire video is masked in green color.

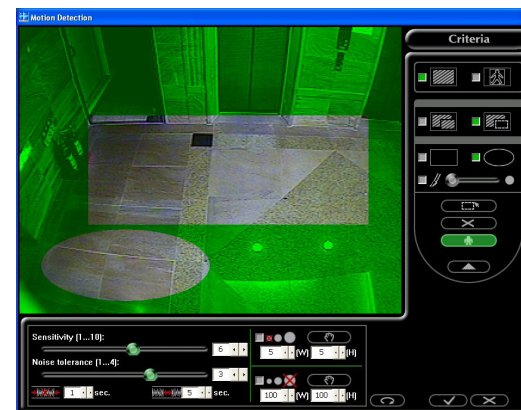
2. Click the **Rectangle Shape**.

3. Drag a rectangle shape in the mask for the area you want detected.



4. Click the **Circular Shape**.

5. Drag a circular shape in the mask for the area you want detected.



6. Click the **Free Hand Sketching**.



7. Use free hand sketching to wipe out Mask areas.



8. You now know how to mask. Mask should help you create a precise detection area.

If the moving video will disturb masking, you can press the Freeze Video button to freeze the video anytime needed.



APPENDIX A: POWER CONSUMPTION

Test Configuration

System Configuration	Sys#1
Chassis	CHASSIS NISE 2110 Ver. A
CPU	Intel® Atom™ processor D525 (1M Cache, 1.80 GHz)
Memory	Apacer 1GB SOD PC3-10600 (industrial)
HDD	N/A
FDD	N/A
CD-ROM	N/A
CompactFlash device	Apacer 8G (industrial)
Power Supply	POWER ADAPTER SPI:G.P FSP65-AAB(N091)
Add-on Card	N/A
CPU Cooler	NISE 2100 HEATSINK
System Fan	N/A
Keyboard	LEMEL B-5201-P
Mouse	GENIVS EASY MOUSE PS/2



Power Consumption Measurement

Purpose

The purpose of the power consumption test is to verify the power dissipation of the system and the load of the power supply.

Test Equipment

PROVA CM-07 AC/DC CLAMP METER

Device Under Test

DUT: Sys #1

Test Procedure

1. Power up the DUT and then boot Windows XP.
2. Enter the standby mode (HDD power down).
3. Measure the power consumption and record it.
4. Run the Burn-in test program to apply 100% full loading.
5. Run the Intel Kpower program.
5. Run the LAN Packet Counter and Receive program.

Test Data

	Sys #1
	+12V
Full-Loading Mode	2.18A
Total	26.16W
Standby Mode	0.9A
Total	10.8W

APPENDIX B: GPIO PROGRAMMING GUIDE

GPIO (General Purpose Input/Output) pins are provided for custom system design. This appendix provides definitions and its default setting for the ten GPIO pins in the NViS 2140H. The pin definition is shown in the following table:

Pin	GPIO Mode	Power On Default	Address	Pin	GPIO Mode	Power On Default	Address
1	VCC	-	-	2	GND	-	-
3	GPO	Low	284h (Bit4)	4	GPI	High	284h (Bit0)
5	GPO	Low	284h (Bit5)	6	GPI	High	284h (Bit1)
7	GPO	Low	284h (Bit6)	8	GPI	High	284h (Bit2)
9	GPO	Low	284h (Bit7)	10	GPI	High	284h (Bit3)

J8 - GPIO connector

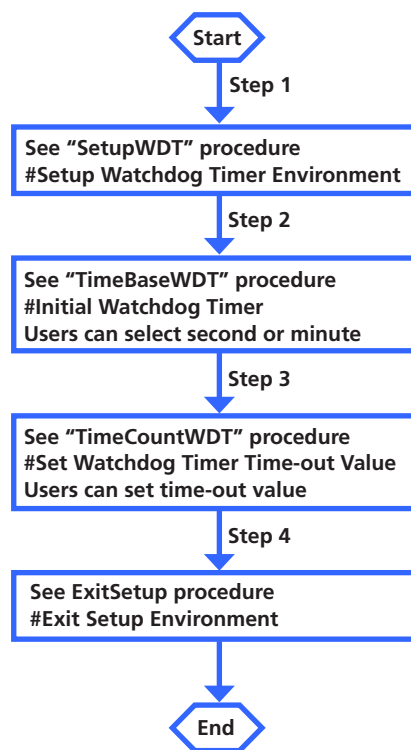
Control the GPO pin (3/5/7/9) level from I/O port 284h bit (4/5/6/7). The bit Set/Clear indicated output High/Low.

GPIO Programming Sample Code

```
#define GPIO_PORT 0x284
#define GPO3 (0x01 << 4)
#define GPO5 (0x01 << 5)
#define GPO7 (0x01 << 6)
#define GPO9 (0x01 << 7)
#define GPO3_HI outportb(GPIO_PORT, 0x10)
#define GPO3_LO outportb(GPIO_PORT, 0x00)
#define GPO5_HI outportb(GPIO_PORT, 0x20)
#define GPO5_LO outportb(GPIO_PORT, 0x00)
#define GPO7_HI outportb(GPIO_PORT, 0x40)
#define GPO7_LO outportb(GPIO_PORT, 0x00)
#define GPO9_HI outportb(GPIO_PORT, 0x80)
#define GPO9_LO outportb(GPIO_PORT, 0x00)
void main(void)
```

```
{  
GPO3_HI;  
GPO5_LO;  
GPO7_HI;  
GPO9_LO;  
}
```

APPENDIX C: WATCHDOG TIMER SETTING



ITE8783 WatchDog Programming Guide

```
#define SUPERIO_PORT 0x2E
#define WDT_SET 0x72
#define WDT_VALUE 0x73
void main(void)
{
    #Enter SuperIO Configuration
    outportb(SUPERIO_PORT, 0x87);
    outportb(SUPERIO_PORT, 0x01);
    outportb(SUPERIO_PORT, 0x55);
    outportb(SUPERIO_PORT, 0x55);
    # Set LDN
    outportb(SUPERIO_PORT,0x07);
    outportb(SUPERIO_PORT+1 ,0x07);
    # Set WDT setting
    outportb(WDT_SET,0xC0); # Use the second to come down
    # If choose the Minute, change value to 0x40
    # Set WDT sec/min
    outportb(WDT_VALUE,0x05); #Set 5 seconds
}
```